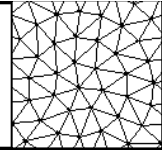


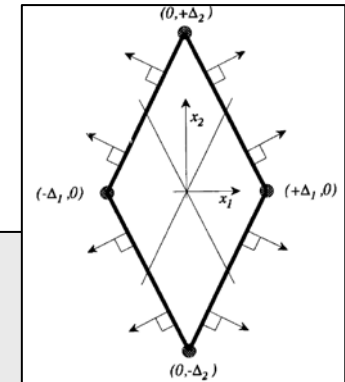
Finite volumes



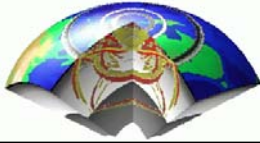
Finite volumes ...

A numerical method based on a **discrete** version of **Gauss' theorem**.

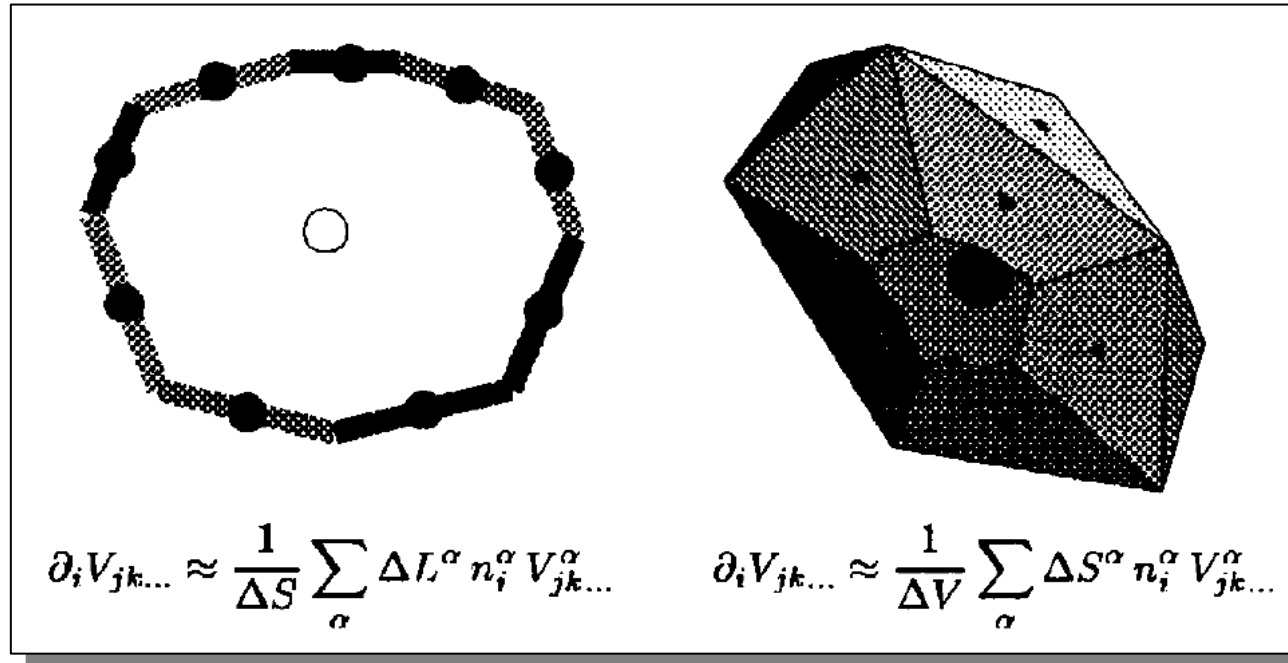
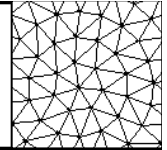
- The theoretical basis
- Derivation of weights for basic grid cells
- FV for hexagonal and irregular grids



... this lecture based on :
Dormy E. and Tarantola A., *J. Geophys. Res.*, 100, 2123-2133, 1995.
Käser, M., Diplomarbeit LMU, 2000.

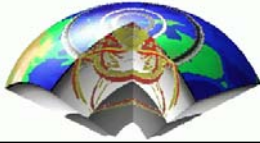


Finite volumes - basic theory

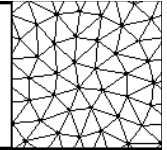


... as the figure suggests, the FV method is based on the idea of knowing a 3D field at the sides of a surface surrounding a **finite volume**. Is there a mathematical theorem relating the (vector) fields inside a volume with the values at its surface? ... Yes, it's **Gauss' theorem**

...

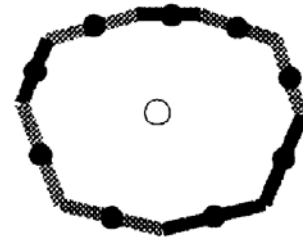


Finite volumes - Gauss' theorem

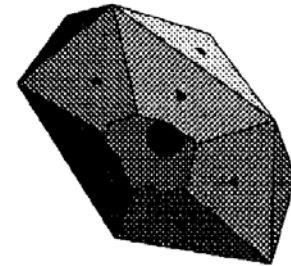


Gauss' theorem:

(by the way one of the most important results on mathematical physics)



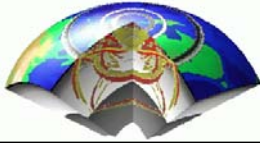
$$\partial_i V_{jk\dots} \approx \frac{1}{\Delta S} \sum_{\sigma} \Delta L^{\sigma} n_i^{\sigma} V_{jk\dots}^{\sigma}$$



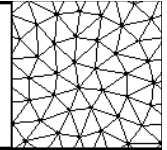
$$\partial_i V_{jk\dots} \approx \frac{1}{\Delta V} \sum_{\sigma} \Delta S^{\sigma} n_i^{\sigma} V_{jk\dots}^{\sigma}$$

$$\int_V dV \partial_i w_i = \int_S dS n_i w_i$$

S	boundary surrounding V
V	volume inside S
w_i	vector field
n_i	unitary normal to the surface (pointing outwards)

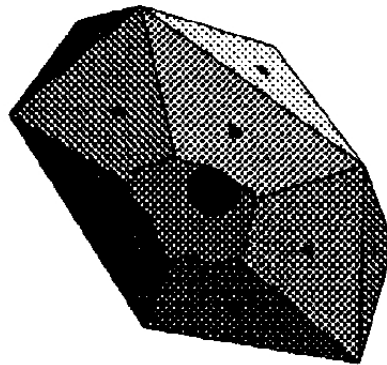
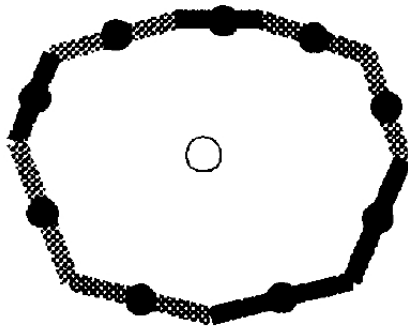
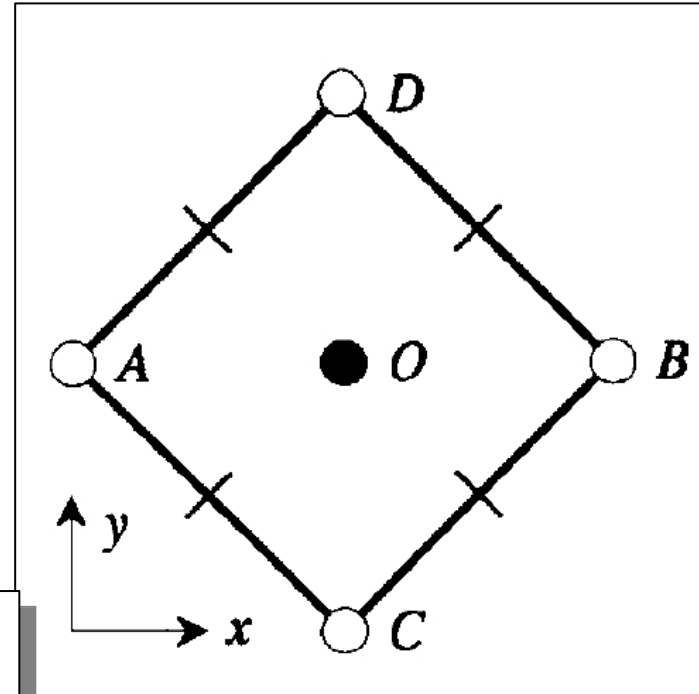


Finite volumes - 2D and 3D



Question:

How can we approximate the gradient of a tensor field at a point P given the values at some points $P_1, P_2, P_3, P_4, P_5, \dots$ around P ?

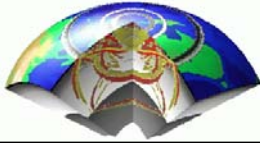


$$\partial_i V_{jk\dots} \approx \frac{1}{\Delta S} \sum_{\alpha} \Delta L^{\alpha} n_i^{\alpha} V_{jk\dots}^{\alpha}$$

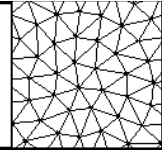
$$\partial_i V_{jk\dots} \approx \frac{1}{\Delta V} \sum_{\alpha} \Delta S^{\alpha} n_i^{\alpha} V_{jk\dots}^{\alpha}$$

$$\int_V dV \partial_i W_{jk} = \int_S dS n_i W_{jk}$$

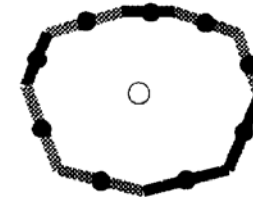
$$\int_S dV \partial_i W_{jk} = \int_L dL n_i W_{jk}$$



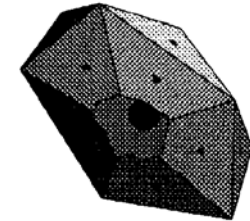
Generalization



Gauss' theorem:
Generalized to the gradient
of for arbitrary tensor
fields ... (e.g. could also be a
scalar field) ...



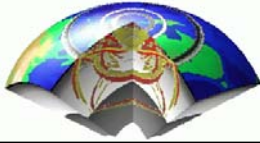
$$\partial_i V_{jk...} \approx \frac{1}{\Delta S} \sum_{\alpha} \Delta l_i^{\alpha} n_i^{\alpha} V_{jk...}$$



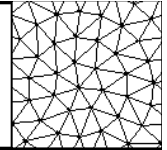
$$\partial_i V_{jk...} \approx \frac{1}{\Delta V} \sum_{\alpha} \Delta S^{\alpha} n_i^{\alpha} V_{jk...}$$

$$\int_V dV \partial_i W_{jk} = \int_S dS n_i W_{jk}$$

W_{jk} arbitrary tensor field
 V volume inside S
 S surface around V
 n_i unitary normal to the surface
(pointing outwards)



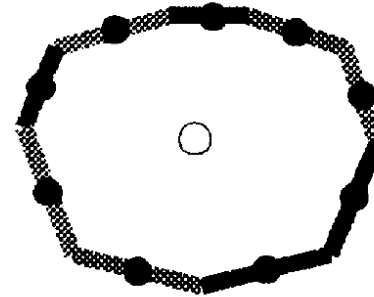
Finite volumes - 3D



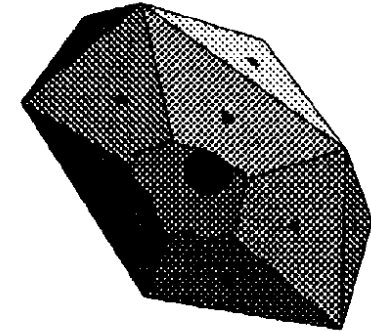
Answer:

We simply need to turn Gauss' theorem into a discrete version!

Assumption: smoothly varying W_{jk}



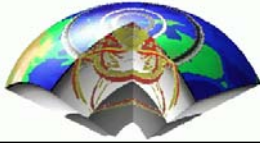
$$\partial_i V_{jk\dots} \approx \frac{1}{\Delta S} \sum_{\alpha} \Delta l^{\alpha} n_i^{\alpha} V_{jk\dots}^{\alpha}$$



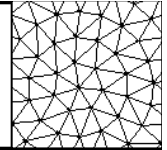
$$\partial_i V_{jk\dots} \approx \frac{1}{\Delta V} \sum_{\alpha} \Delta S^{\alpha} n_i^{\alpha} V_{jk\dots}^{\alpha}$$

$$\partial_i W_{jk} \approx \frac{1}{\Delta V} \sum_{\alpha} \Delta S_{\alpha} n_i^{\alpha} W_{jk}^{\alpha}$$

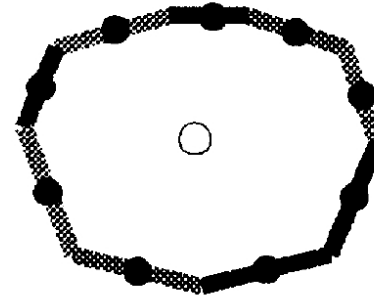
W_{jk}	arbitrary tensor field
ΔV	total volume
ΔS_{α}	surface segment
n_i	unitary normal to the surface
α	number of surface segments



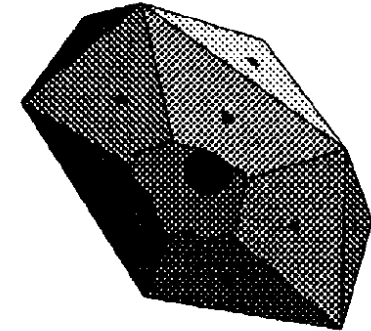
Finite volumes - 2D



$$\partial_i W_{jk} \approx \frac{1}{\Delta S} \sum_{\alpha} \Delta L_{\alpha} n_i^{\alpha} W_{jk}^{\alpha}$$



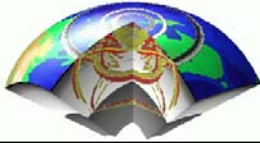
$$\partial_i V_{jk\dots} \approx \frac{1}{\Delta S} \sum_{\alpha} \Delta L_{\alpha} n_i^{\alpha} V_{jk\dots}^{\alpha}$$



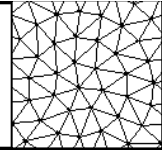
$$\partial_i V_{jk\dots} \approx \frac{1}{\Delta V} \sum_{\alpha} \Delta S_{\alpha} n_i^{\alpha} V_{jk\dots}^{\alpha}$$

W_{jk}	arbitrary tensor field
ΔS	total surface
ΔL_{α}	boundary segment
n_i	unitary normal to the surface
α	number of surface segments

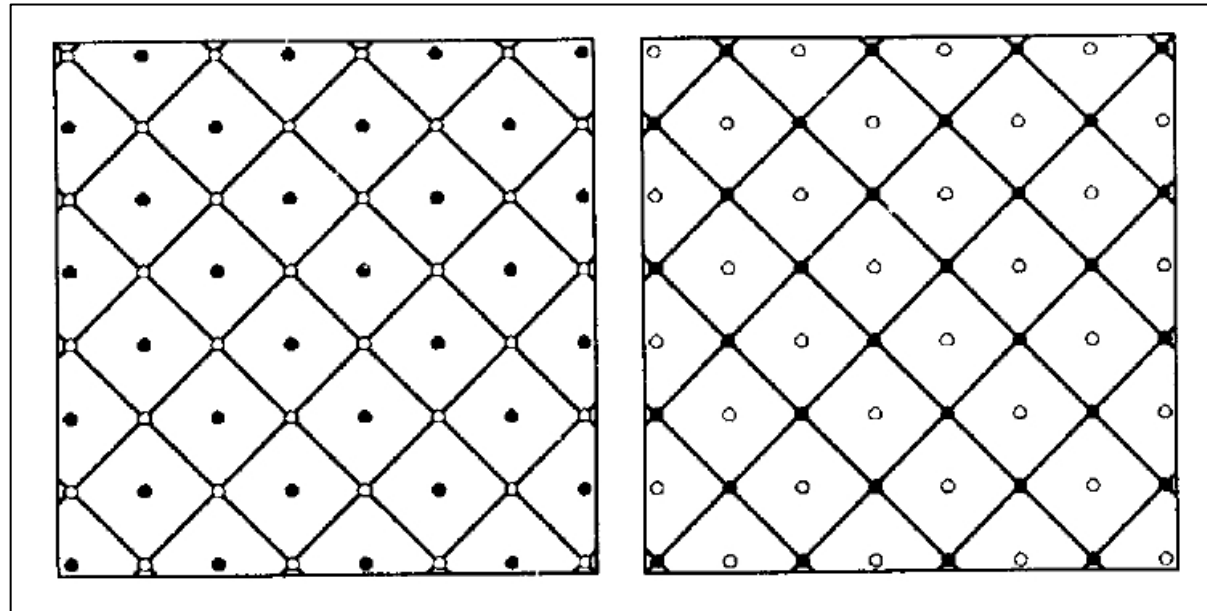
How can we use these ideas to solve p.d.e.'s ?



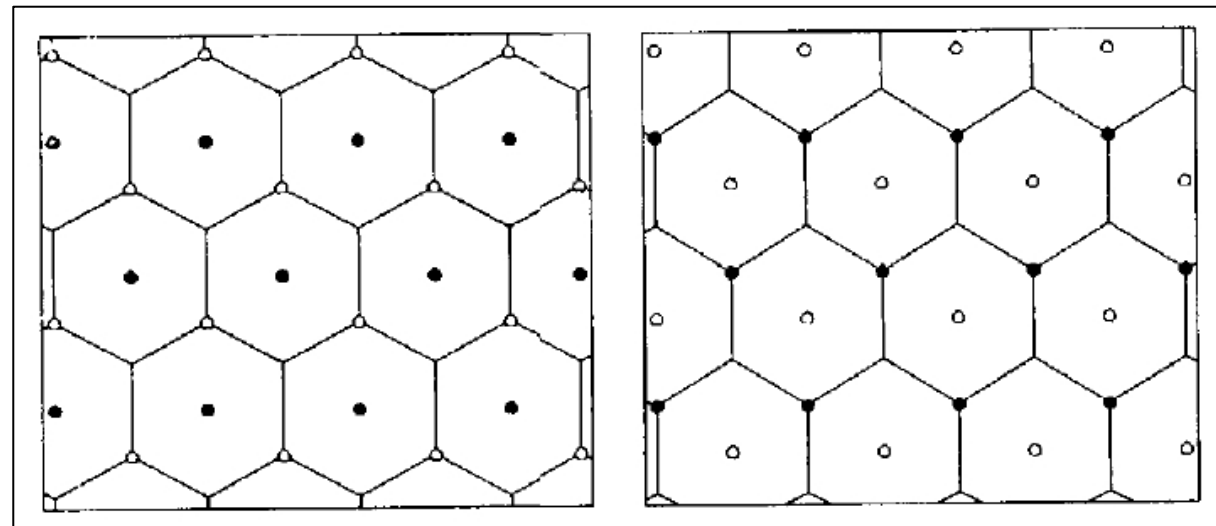
Finite volumes - space grids

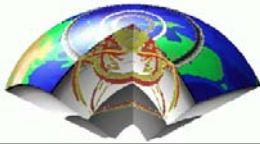


2D Euclidian space
- Lozenges
- staggered grid

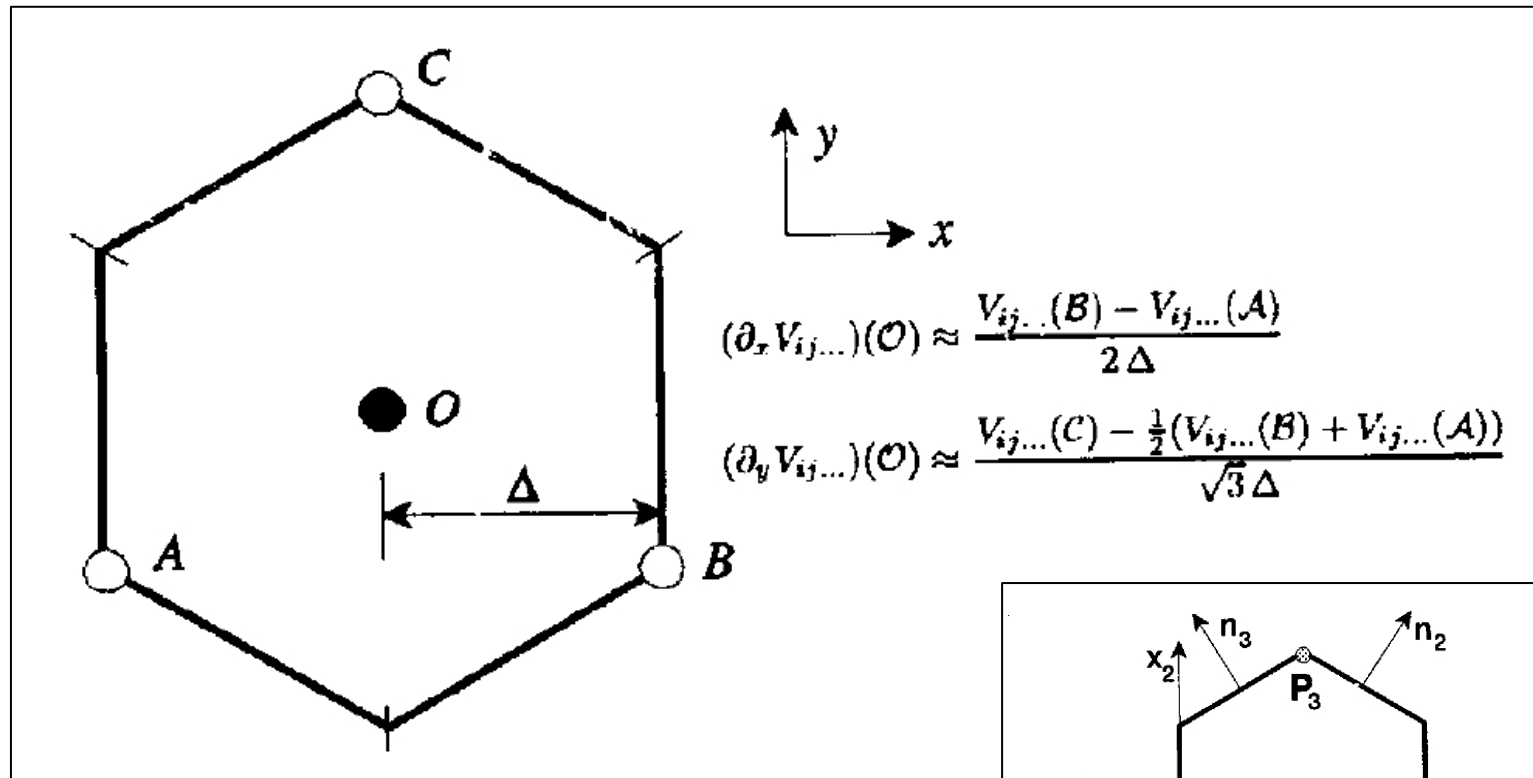
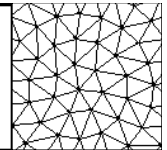


2D Euclidian space
- hexagons
- minimal grid

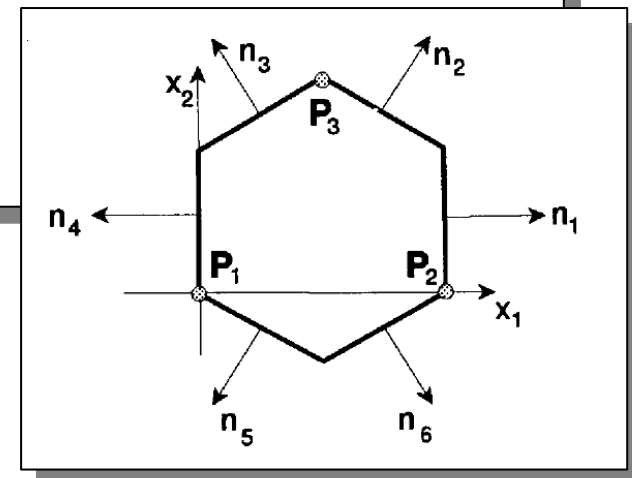


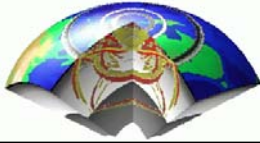


Finite volumes

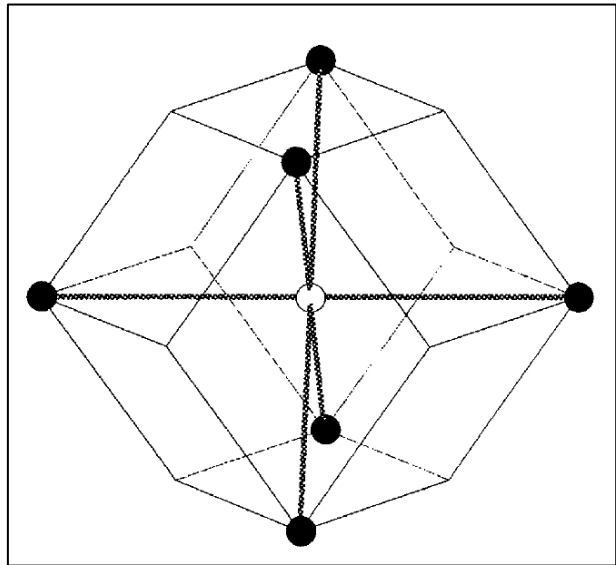
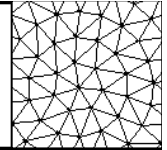


Minimal grid for finite volumes

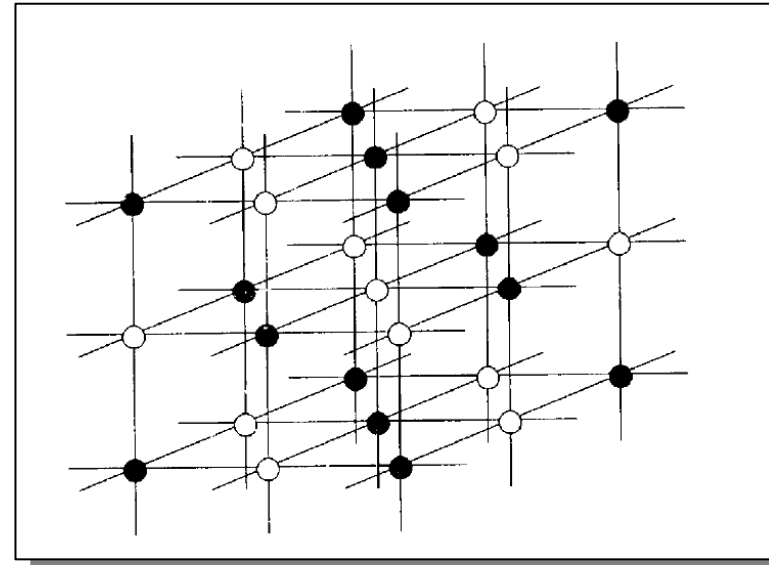




Finite volumes - space grids

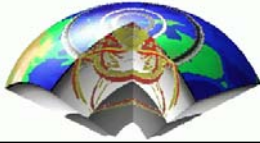


Voronoi cell for FD grid

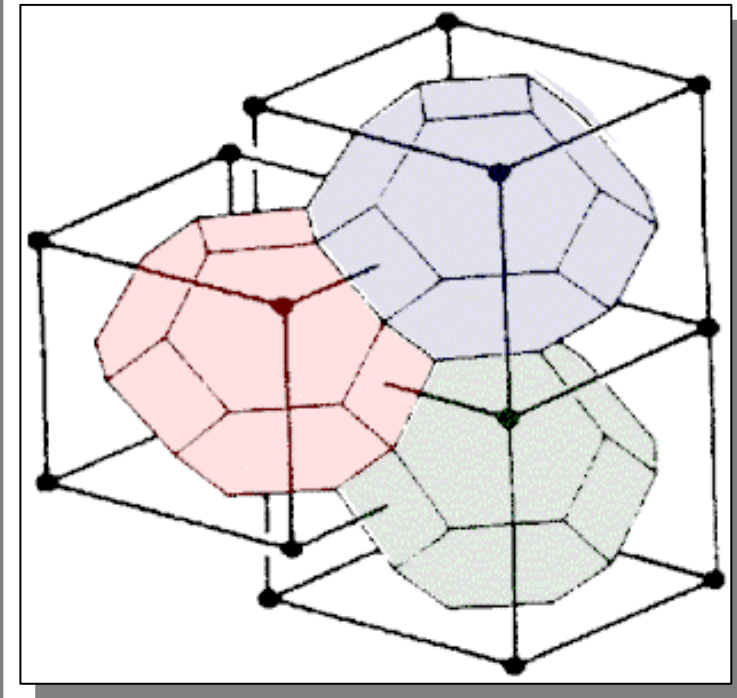
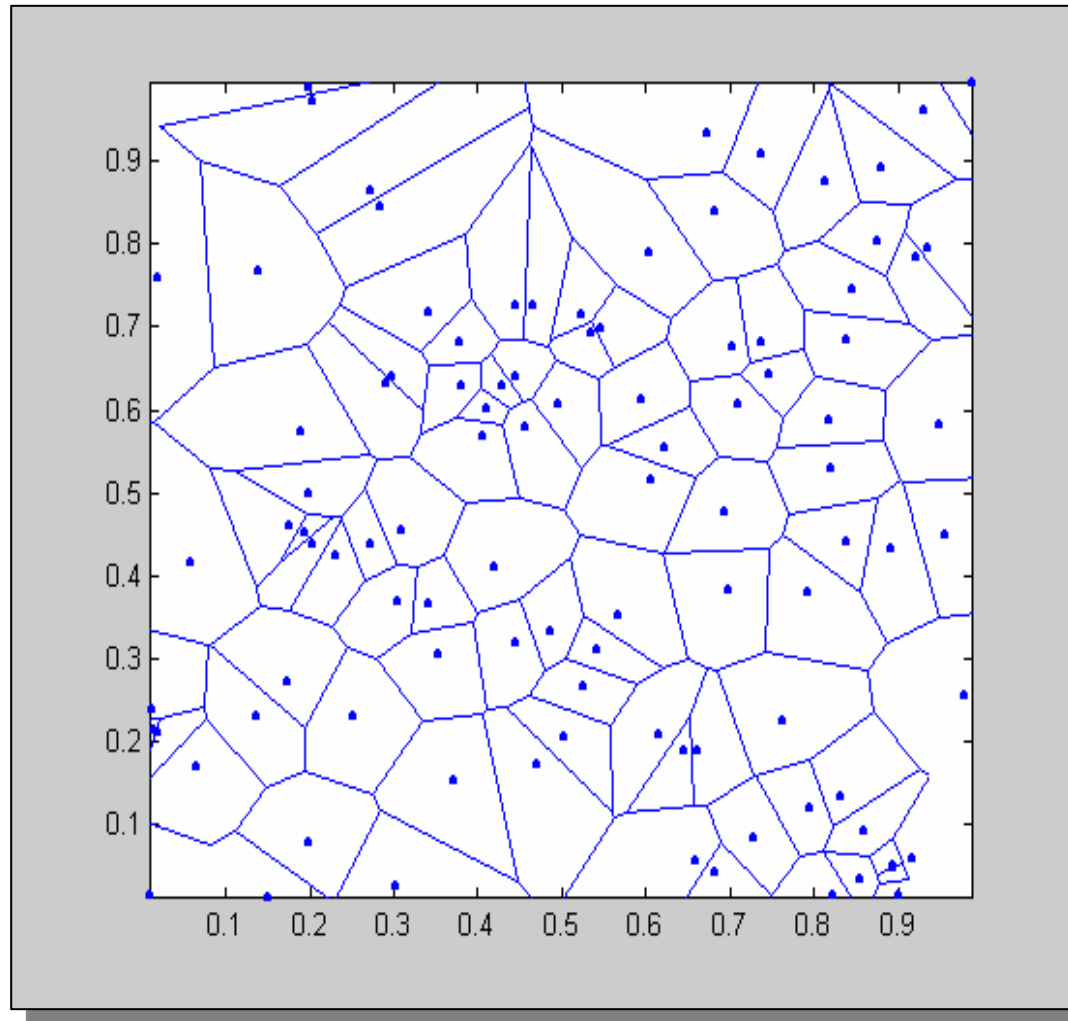
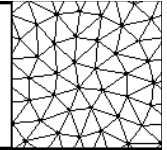


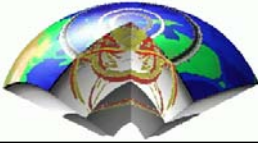
Classic FD grid in 3D

The Voronoi diagrams of an unstructured set of nodes divides the plane into a set of regions, one for each node, such that any point in a particular region is closer to that regions node than to any other.

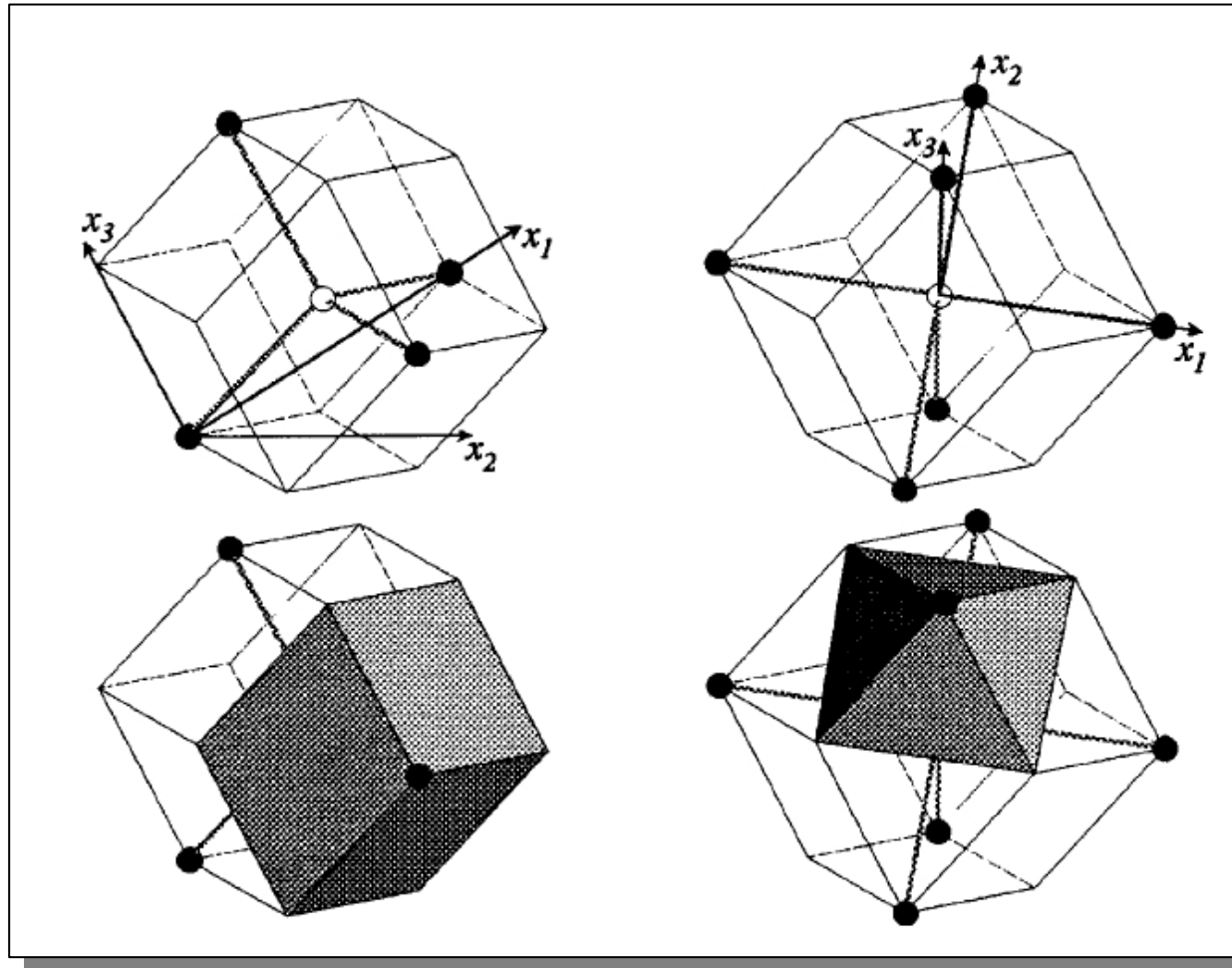
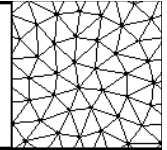


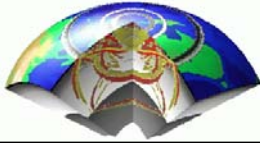
Voronoi cells



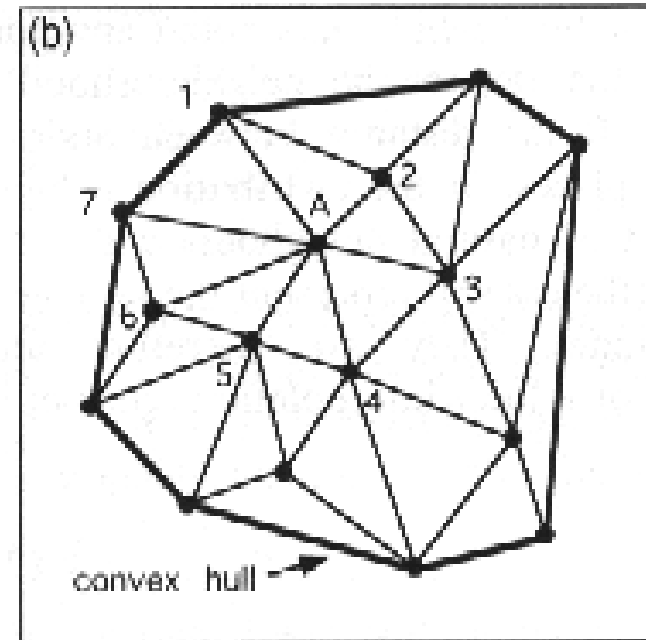
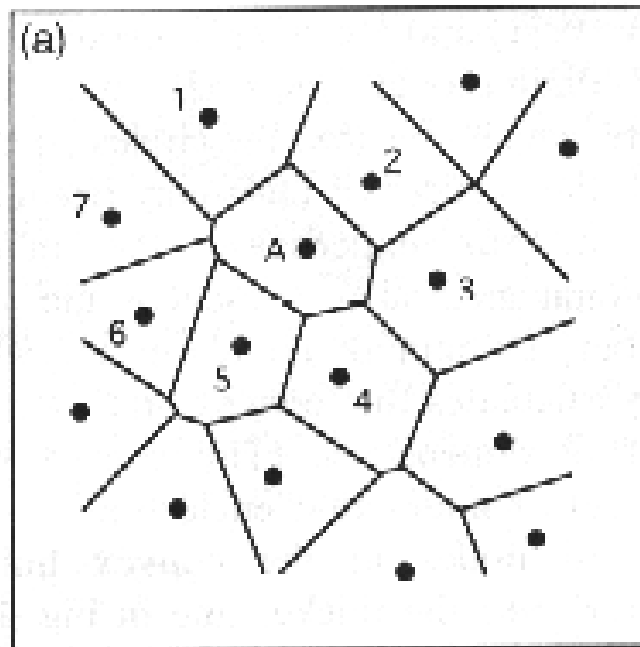
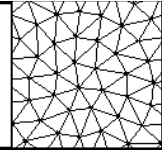


Finite volumes - volumes and surfaces

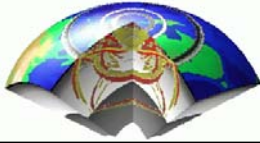




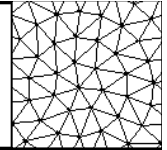
Voronoi and Delaunay

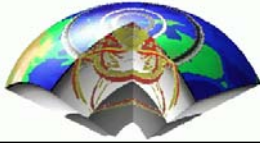


Delaunay triangles are obtained by linking the vertices of neighbouring Voronoi cells

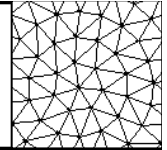


Voronoi Cells in Nature

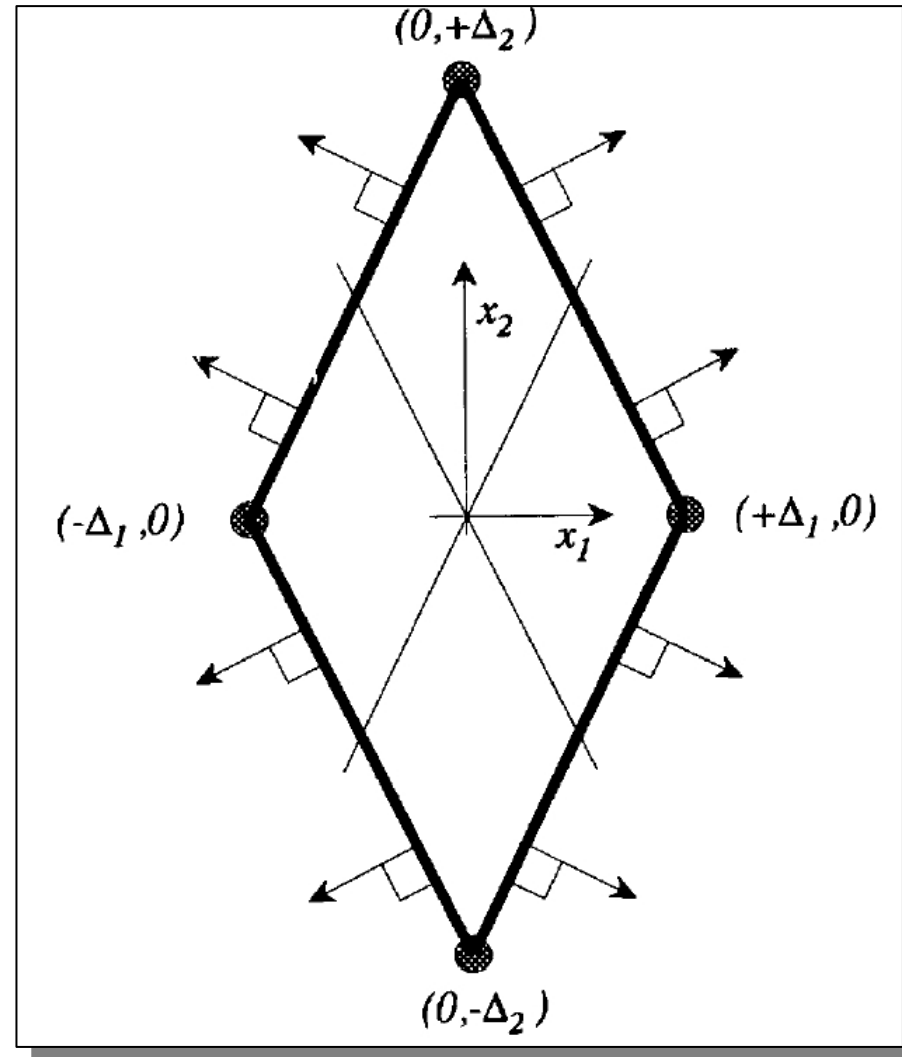


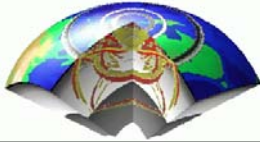


Finite volumes - Difference weights

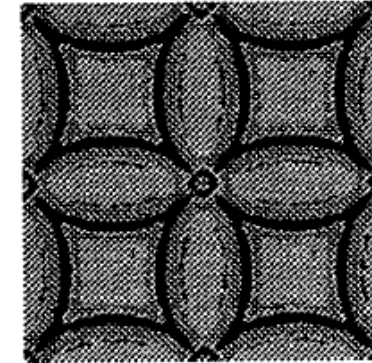
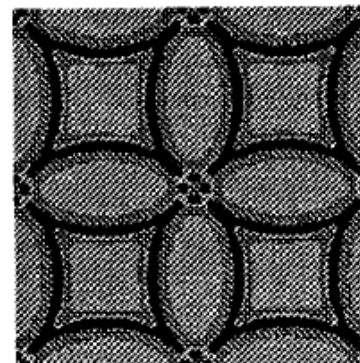
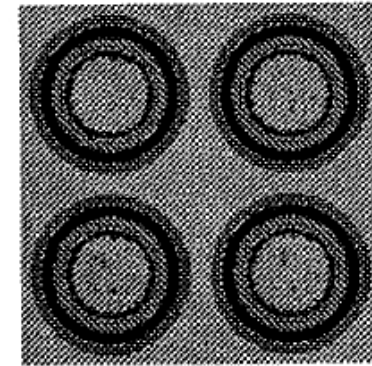
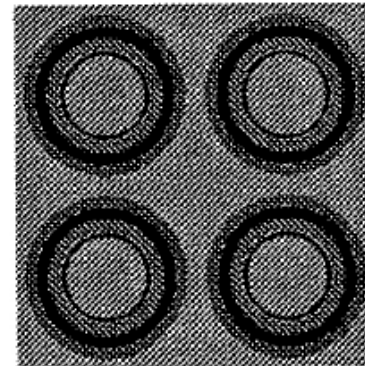
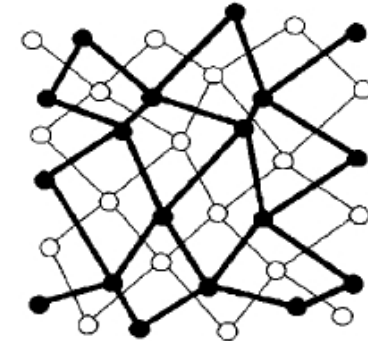
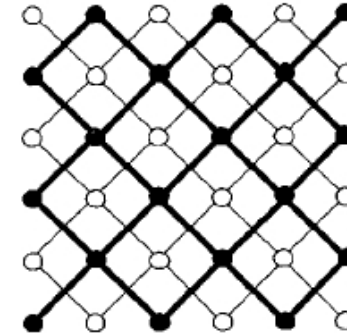
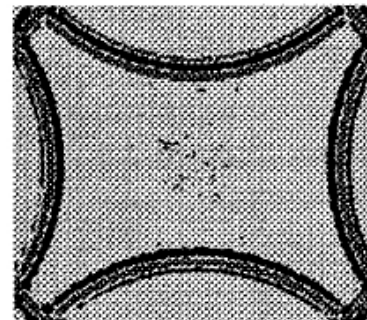
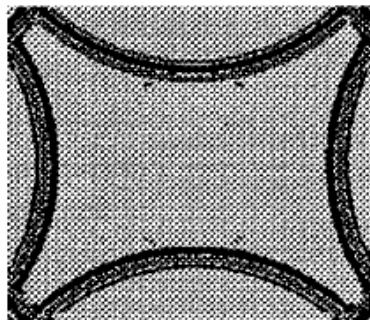
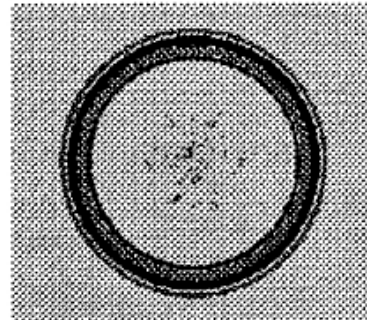
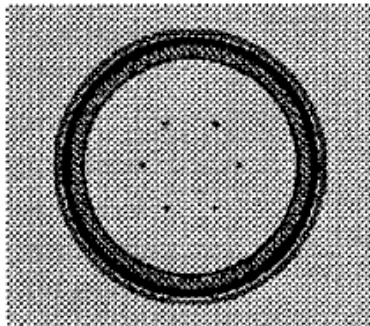
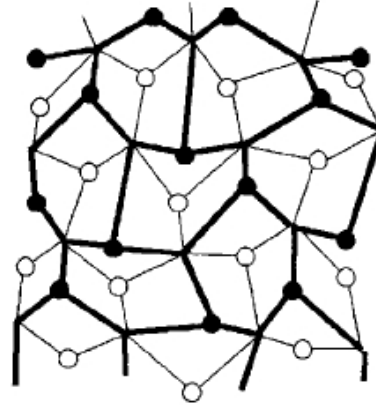
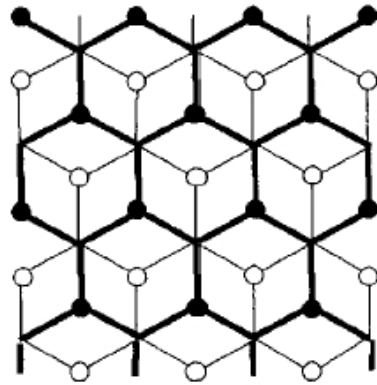
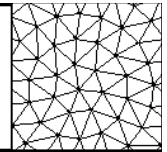


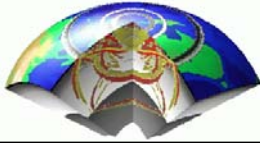
Let us calculate the difference operators for a simple finite volume cell



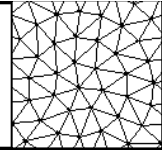


Finite volumes - wave propagation

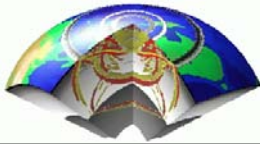




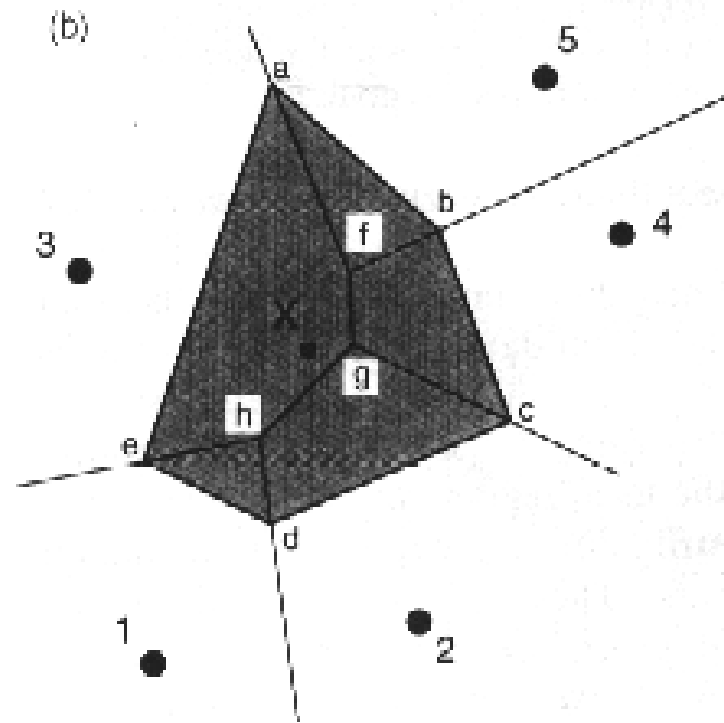
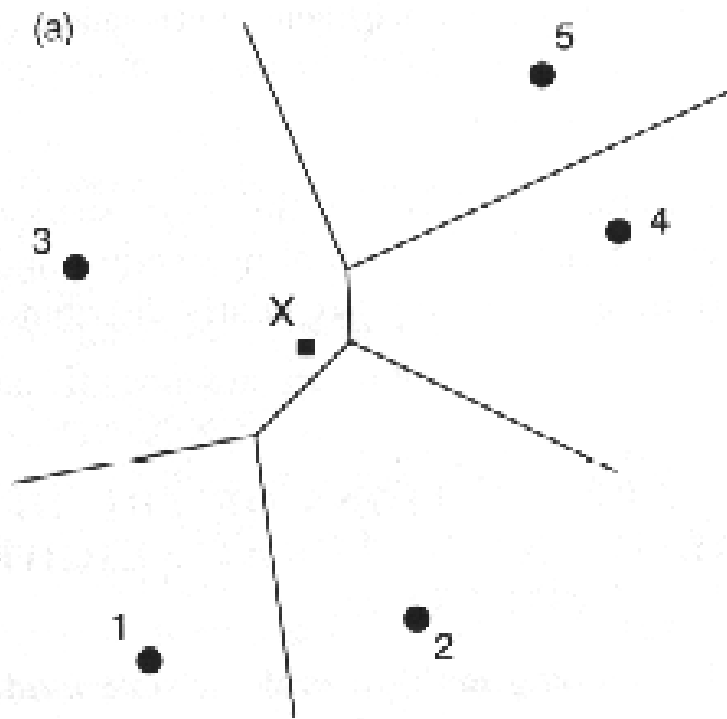
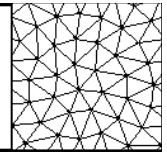
Natural Neighbours

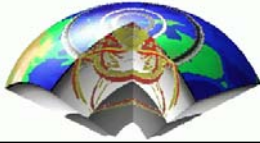


- Basis for local interpolation
- Linear interpolation using triangles
- Distance weighting
- Natural neighbour interpolation
- Differential weights
- Examples

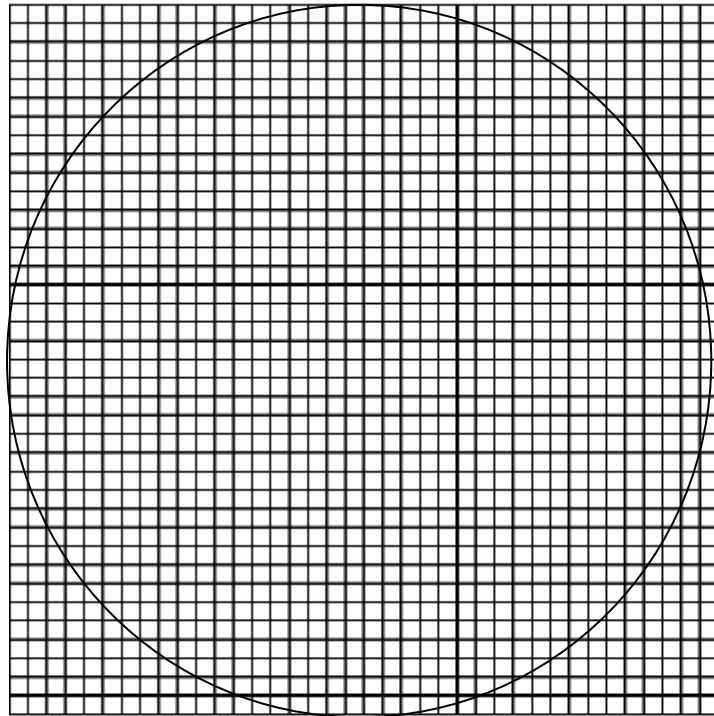
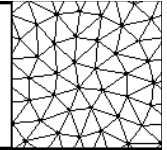


Voronoi: Overlapping Regions

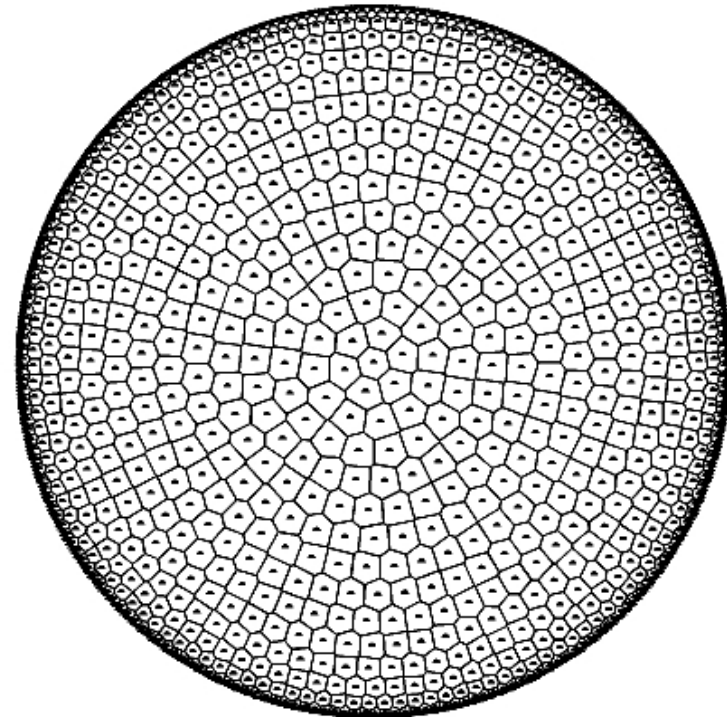




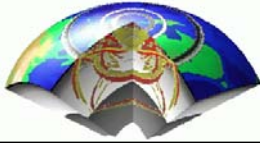
Unstructured Grid Methods



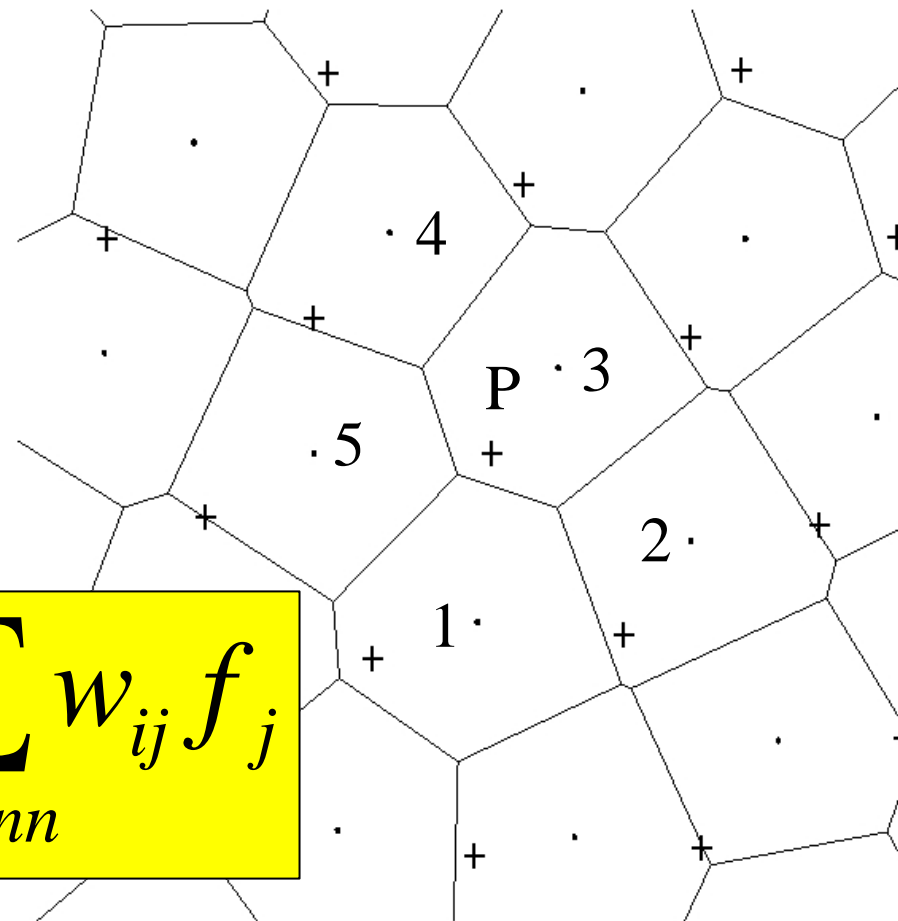
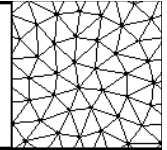
Regular Grid



Voronoi cells



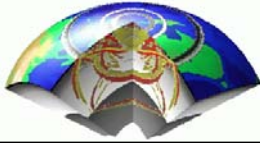
Waves on unstructured grids



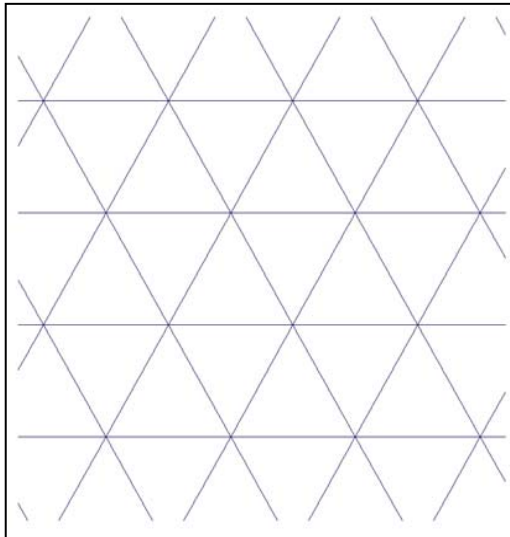
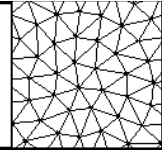
- + Primary grid (velocities)
- . Secondary grid (stresses)

Point P
with 5 natural
neighbours

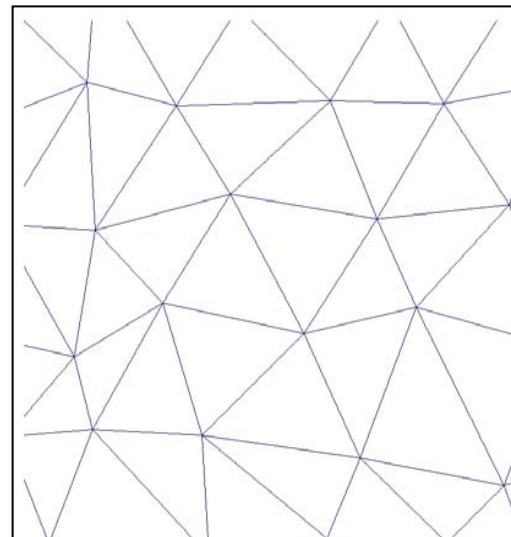
$$\partial f_P^i = \sum_{j=1,nn} w_{ij} f_j$$



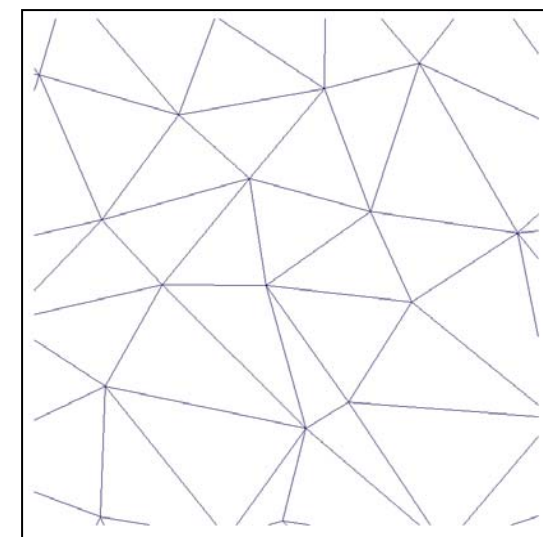
Triangular grid quality



$$q_{\text{mean}}=1.0$$



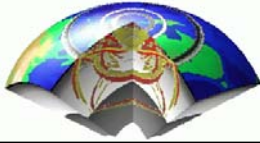
$$q_{\text{mean}}=0.9$$



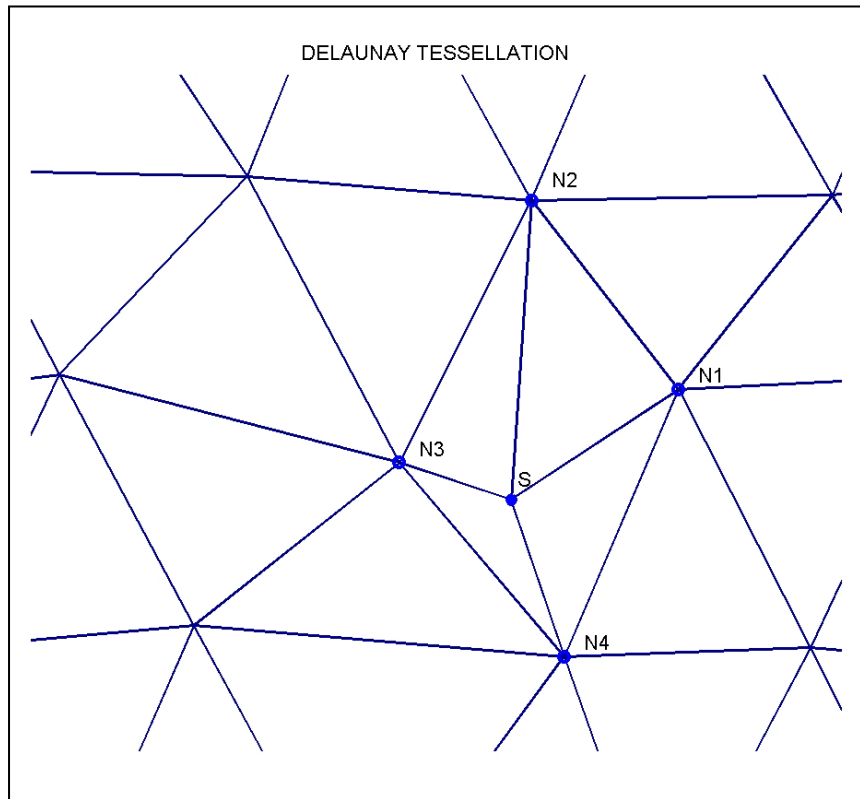
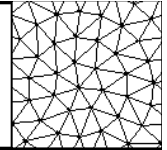
$$q_{\text{mean}}=0.8$$

$$q = \frac{4\sqrt{3}A}{a^2 + b^2 + c^2}$$

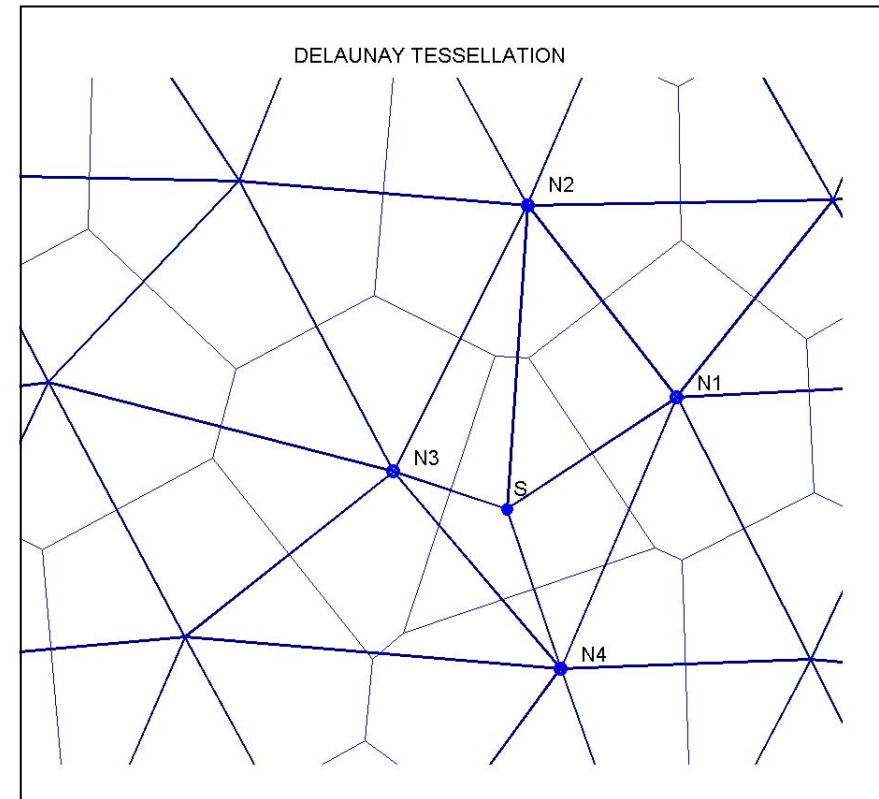
Triangle quality q



Method 1: Natural Neighbour Coordinates

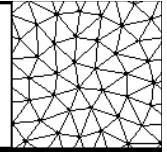
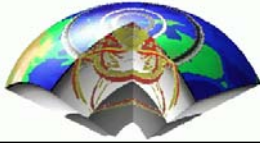


Triangulation

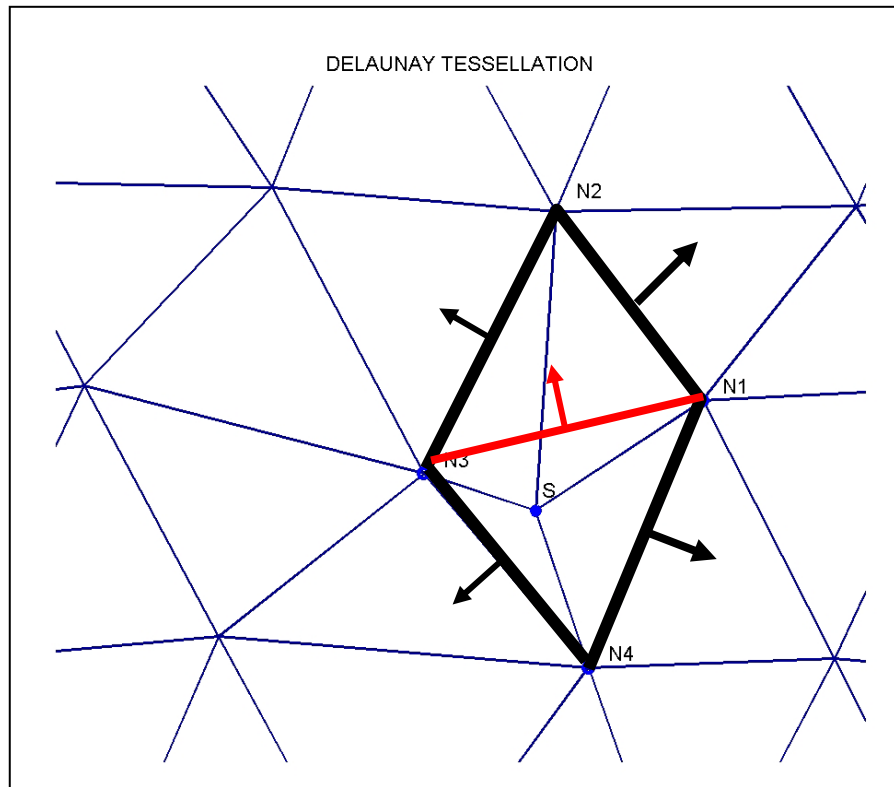


Voronoi Cells

Interpolation (and differential weights for natural neighbours are calculated using overlapping Voronoi cells).



Method 2: ~~The Finite Volume Method~~

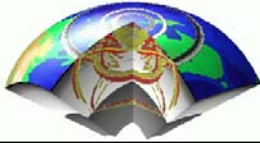


The Finite Volume method is based on a discretization of Gauss' Law

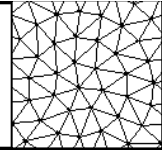
$$\partial_i f = \frac{1}{\Delta S} \sum_{j=1}^{NN} \Delta L_{ij} n_{ij} f_j$$

Note that the position of point S is irrelevant!

Surprising result! Using only three points is more accurate than using all natural neighbours!



Test Function



Test function f_p on primary grid points x_i :

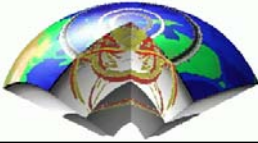
$$f_p(x_i) = \sin(\underline{k} \underline{x}_i - wt)$$

Analytical derivative $f^{(j)}$ on secondary grid points x_k :

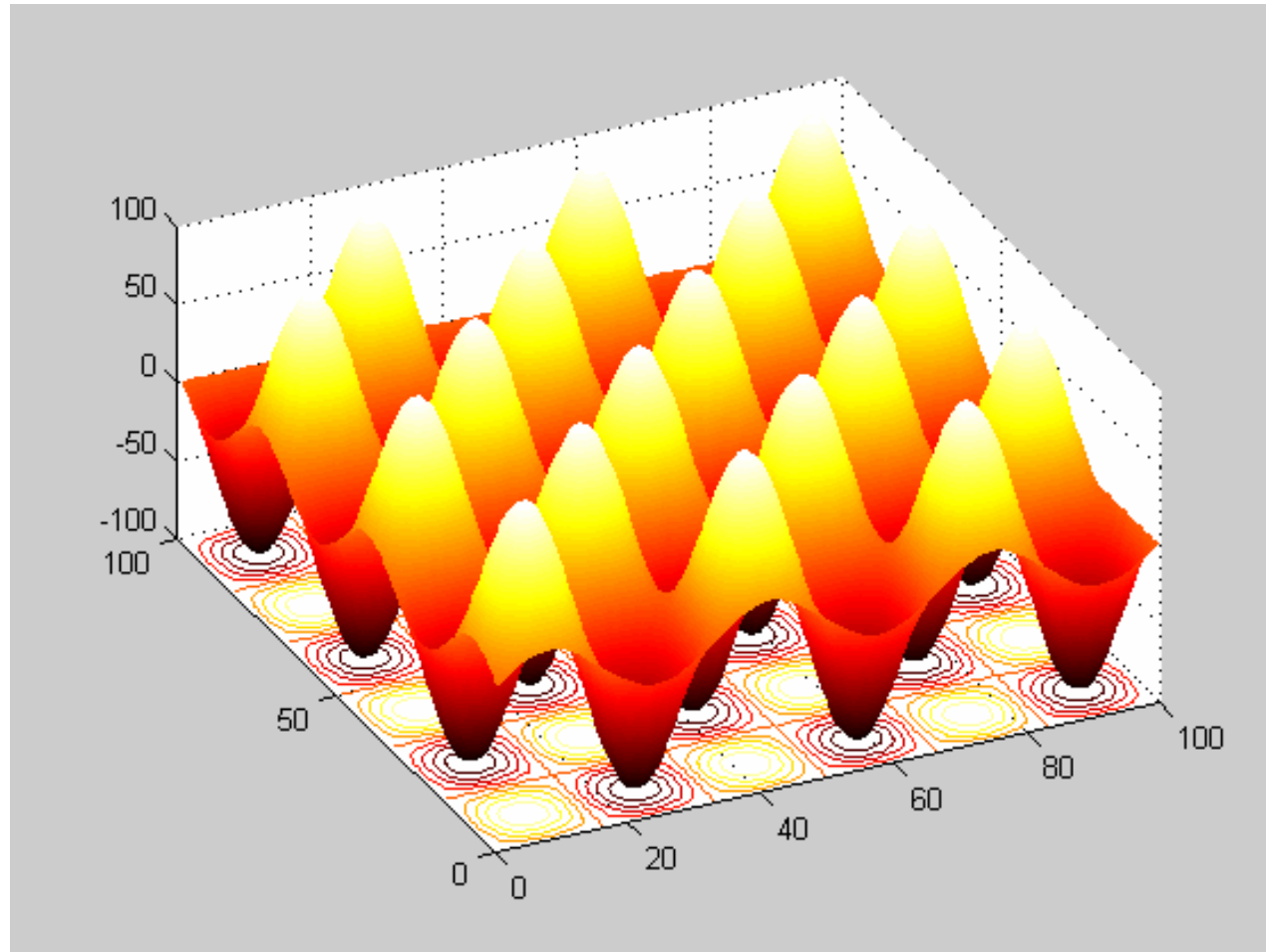
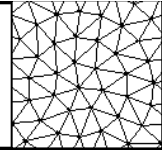
$$f_s^{(j)}(x_k) = k_j \cos(\underline{k} \underline{x}_k - wt)$$

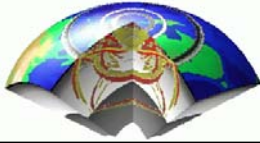
Error of numerical derivative on sec. grid

$$\varepsilon(\underline{k}, q_{mean}) = \frac{\sum_k (\tilde{f}^{(j)}(x_k) - f(x_k))^2}{\sum_k f^2(x_k)}$$

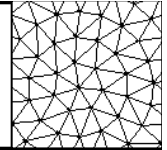


Test Function

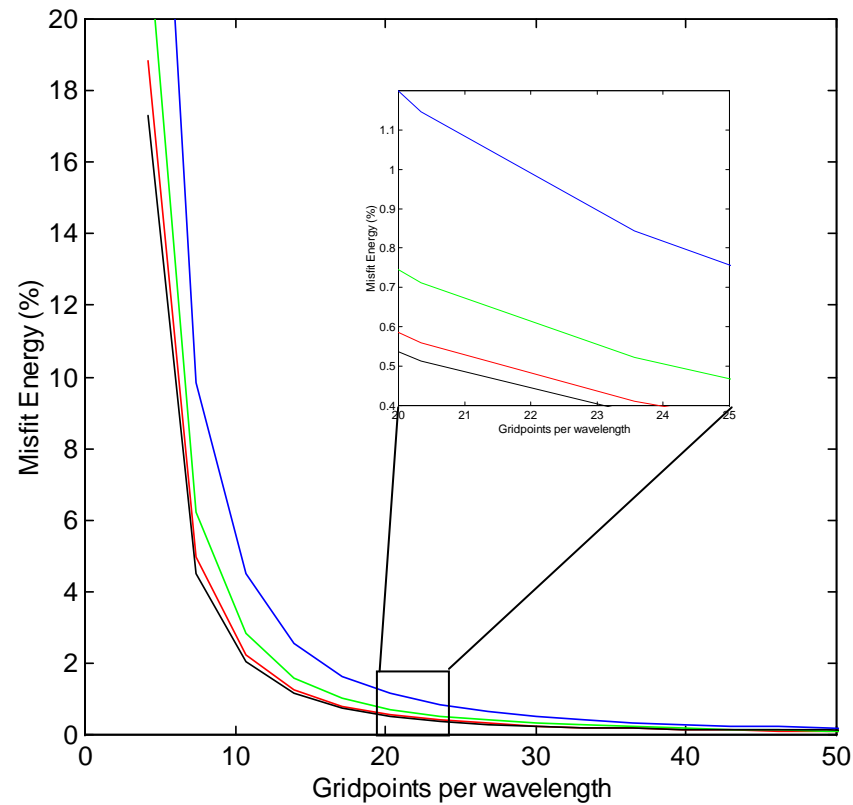




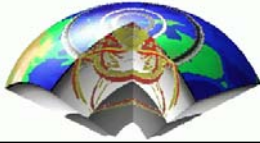
Error of space derivative



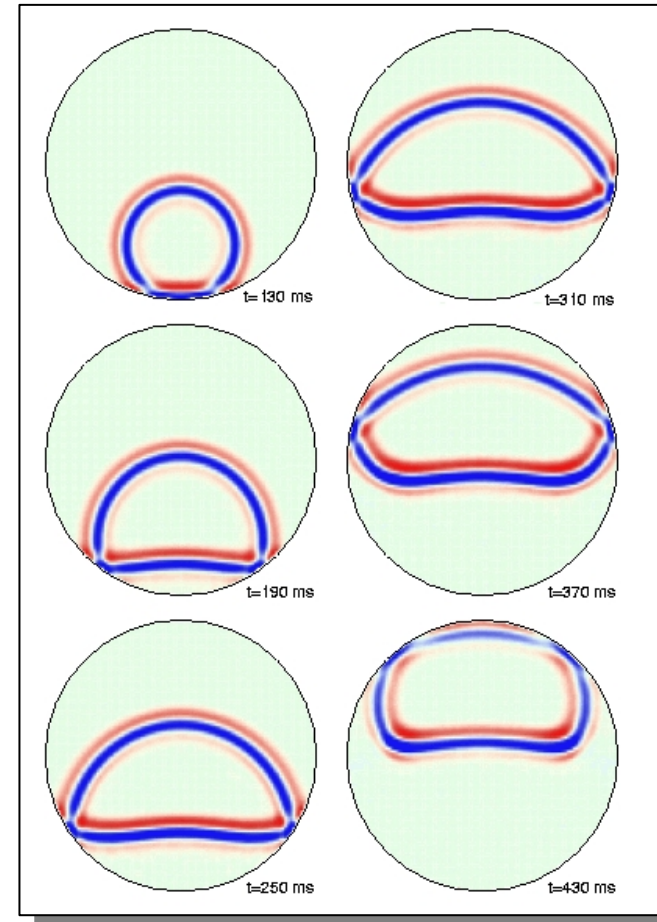
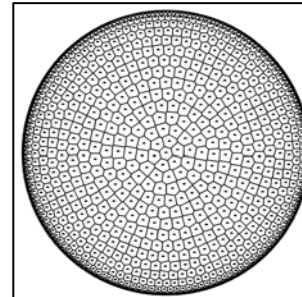
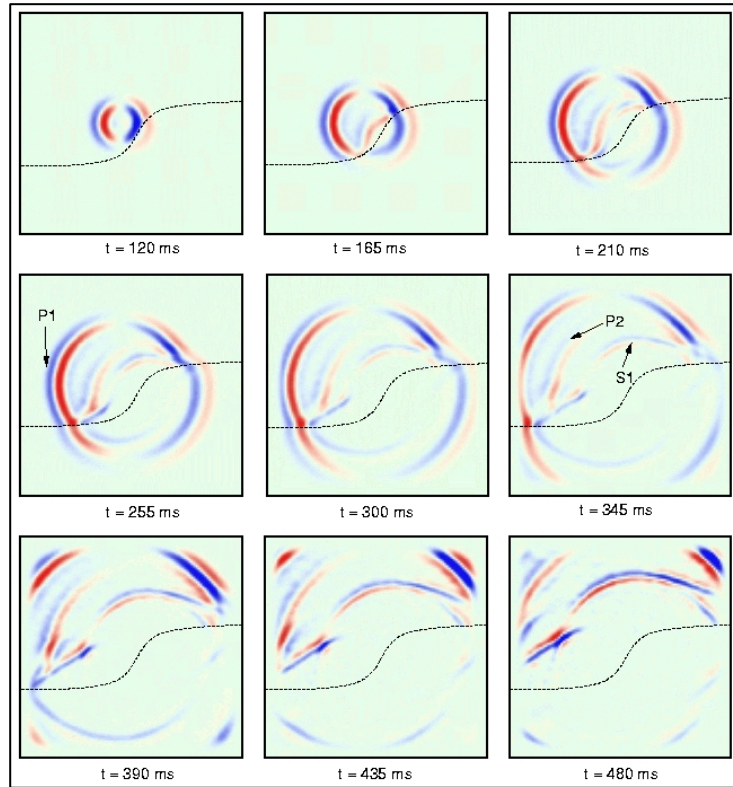
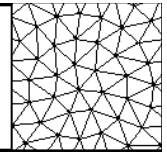
Irregular Grid - $q^{\text{mean}} = 0.8$



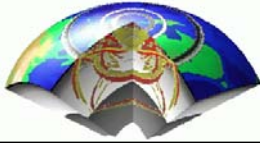
black - Magnier
green - NN
blue - FV(NN)
red - FV (3 points)



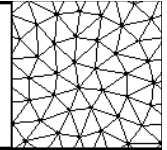
Waves with natural neighbours



Käser, Igel, Sambridge, Braun, 2001
Käser and Igel, 2001



Finite volumes: summary



The **finite volume method** is an elegant approach to solving partial differential equations on unstructured grids.

The finite volume method is based on a discretization of **Gauss' theorem**.

The FV method is frequently applied to **flow problems**. High-order approaches have been recently developed.

The FV method requires the calculation of volumes and surfaces for each cell. This requires the calculation of **Voronoi cells** and **triangulation**.