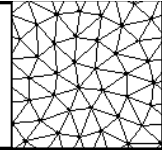


Numerical methods



Motivation

Specific methods:

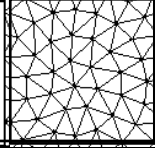
- Finite differences
- High-order FD methods
- Pseudospectral methods
- Finite elements
- Finite volumes

Applications

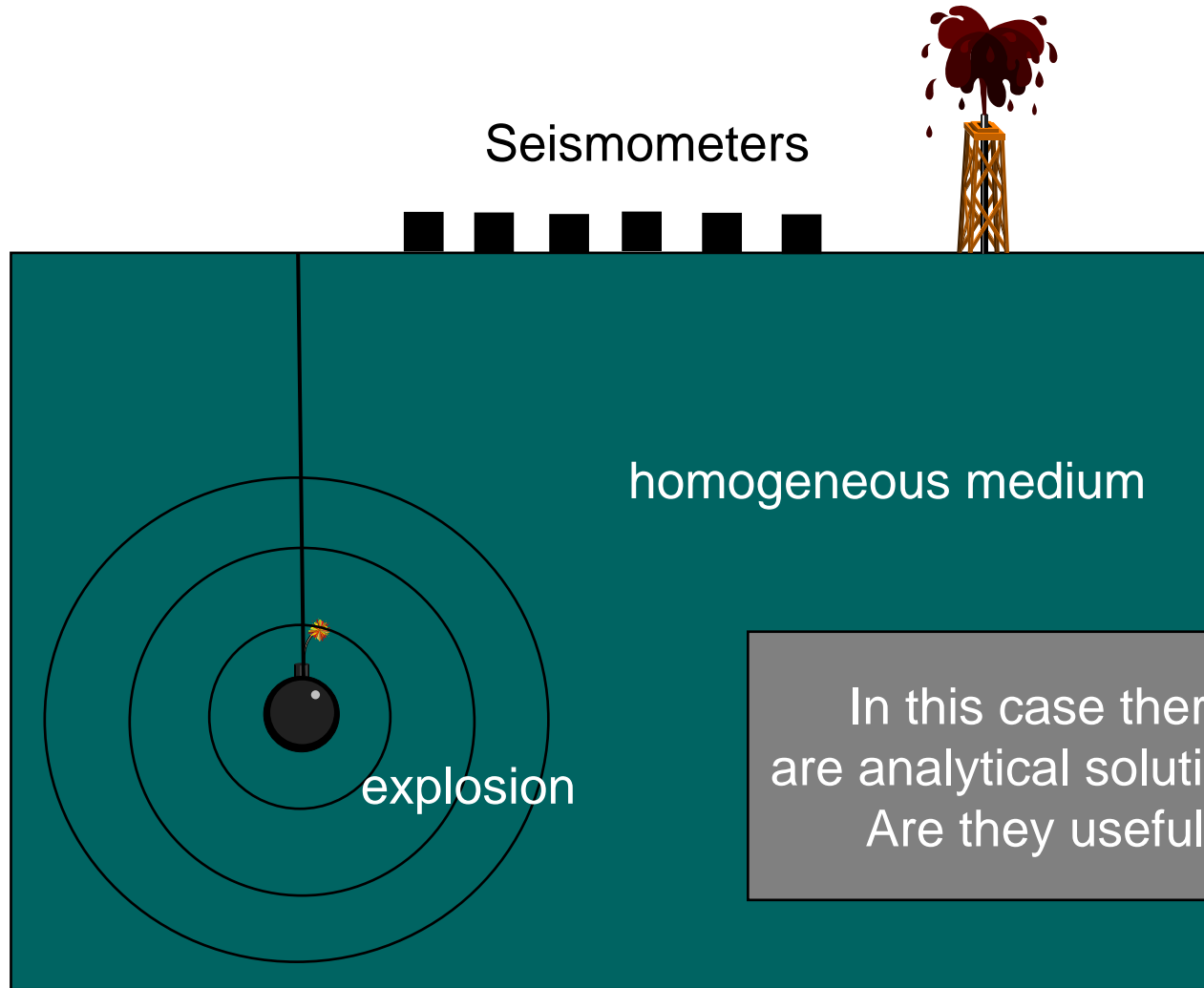
- Wave propagation
- Rupture problems
- Volcano seismology
- Global wave propagation
- Earthquake scenarios



Why numerical methods?



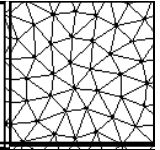
Example: seismic wave propagation



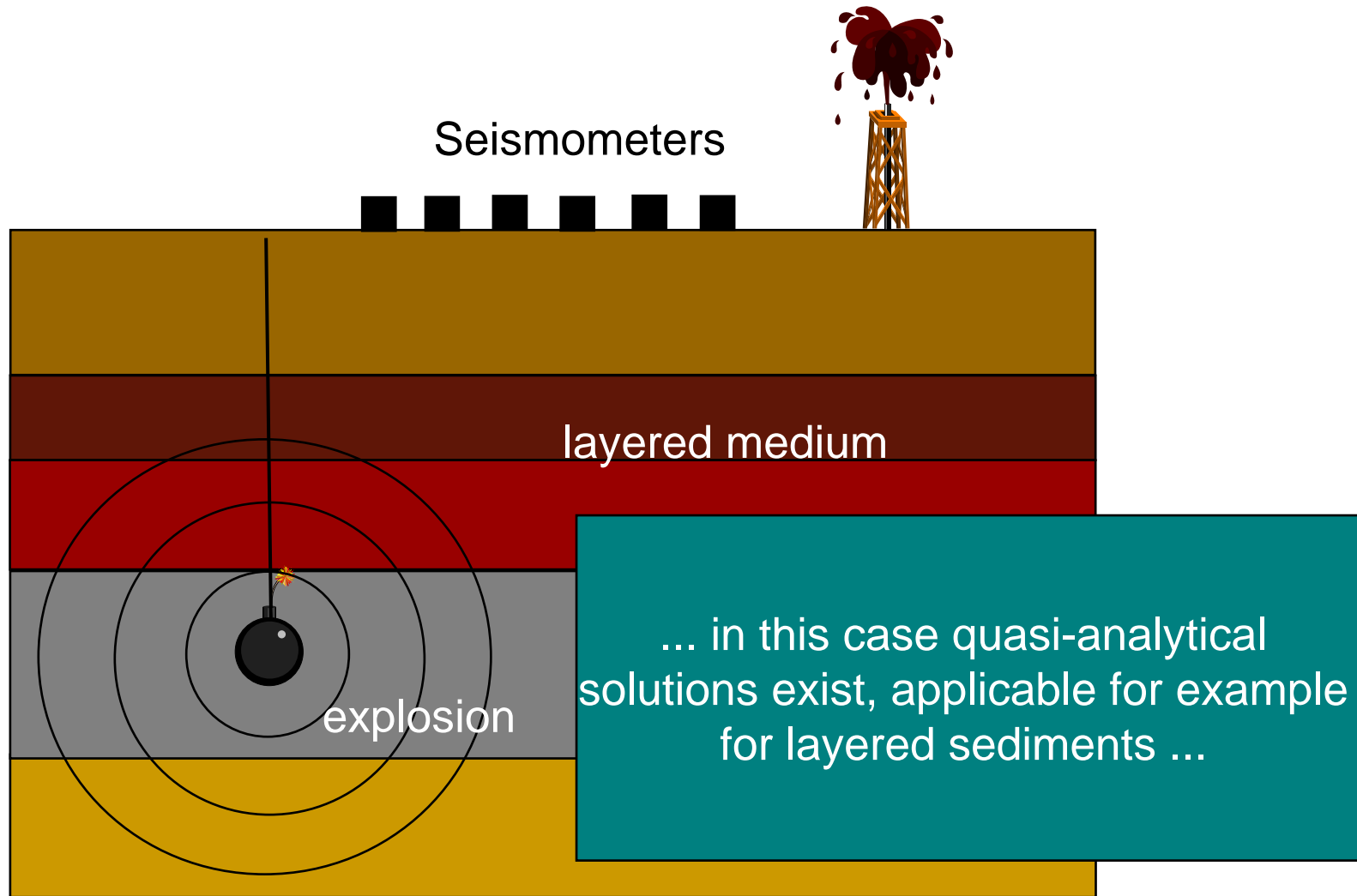
In this case there are analytical solutions?
Are they useful?



Why numerical methods?

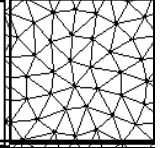


Example: seismic wave propagation

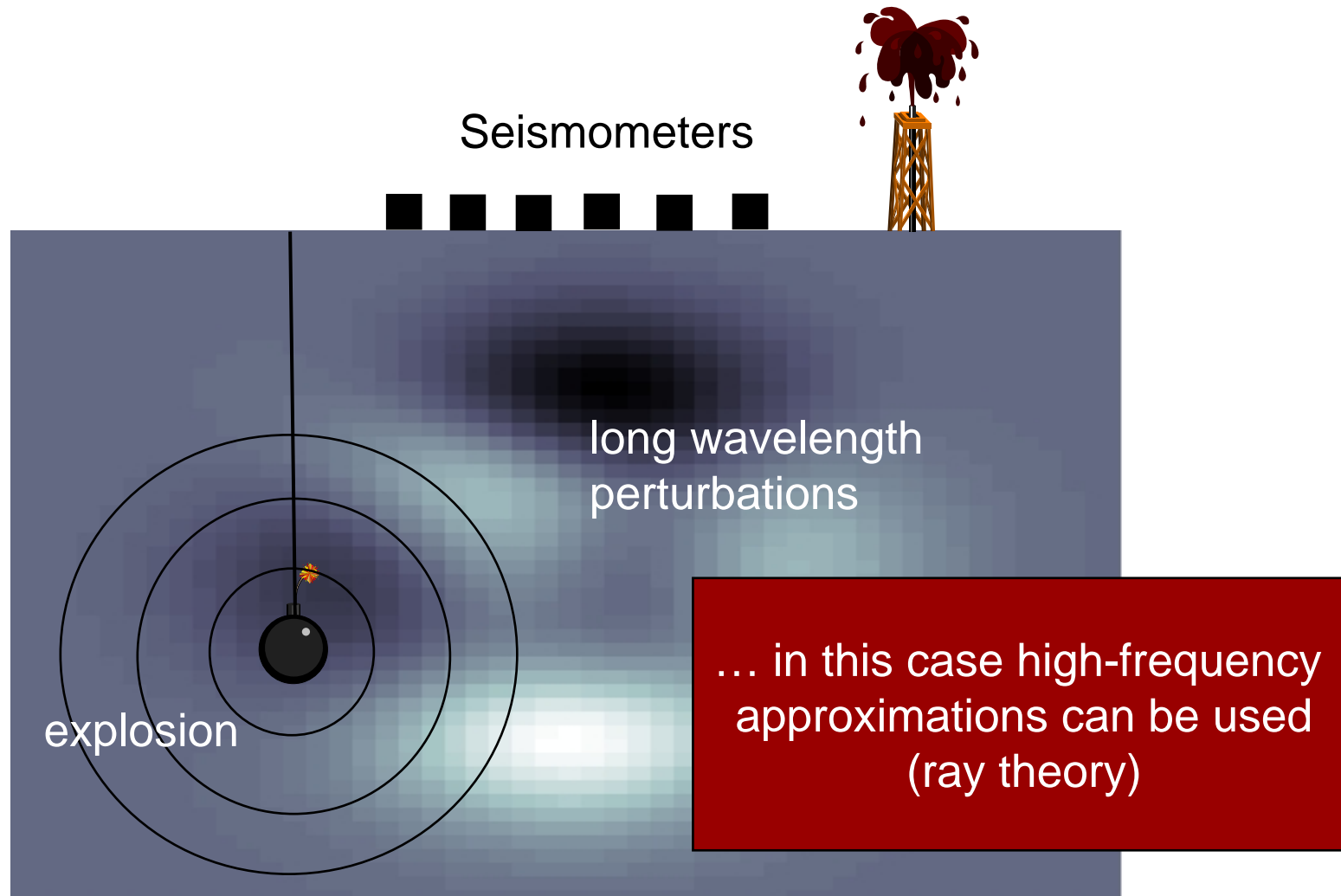




Why numerical methods?

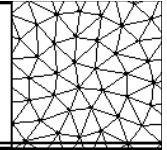


Example: seismic wave propagation

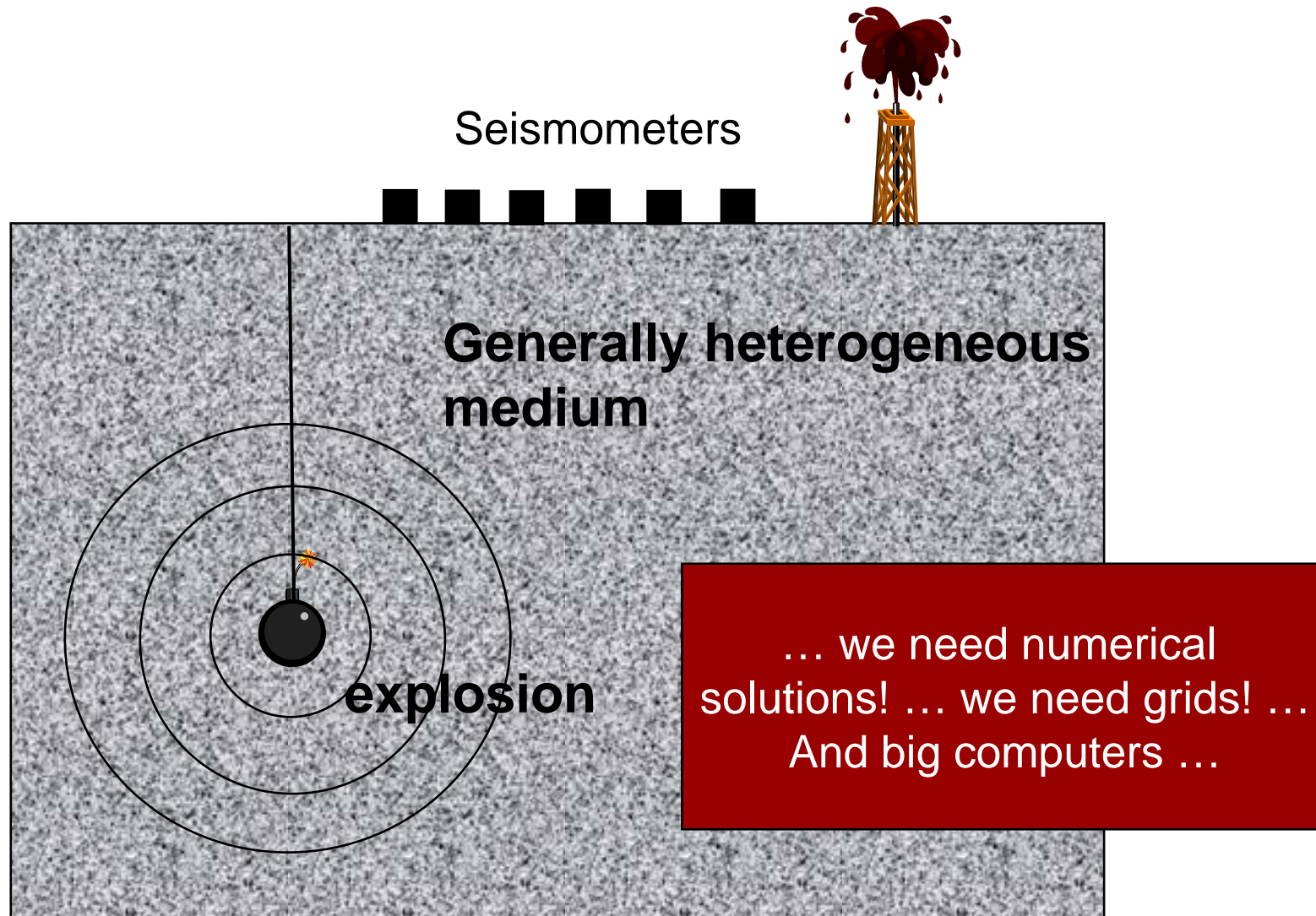


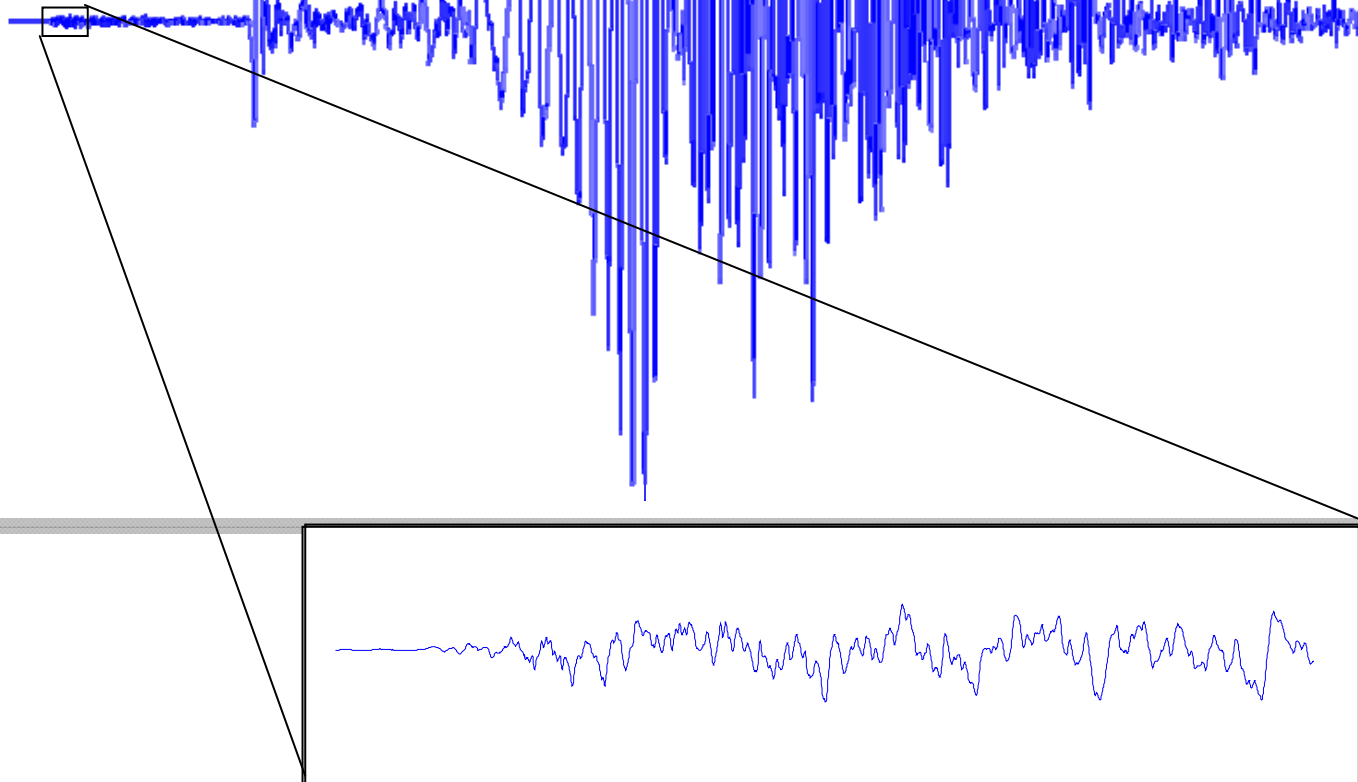
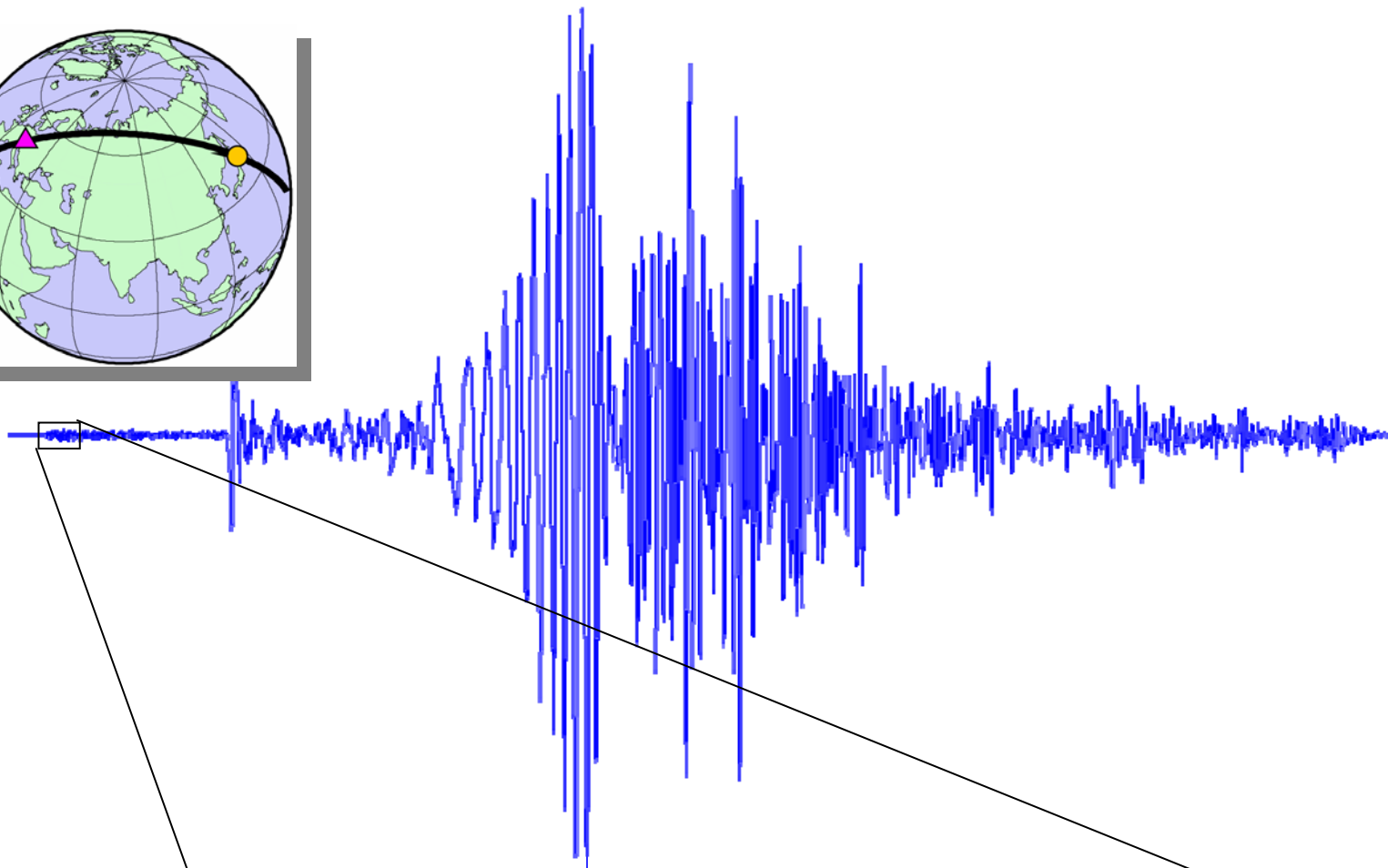
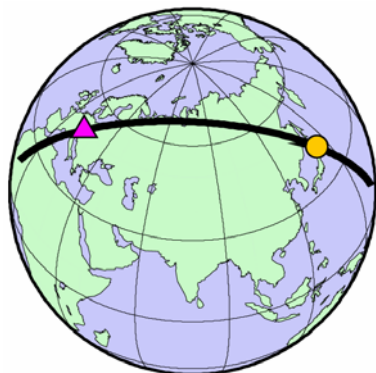
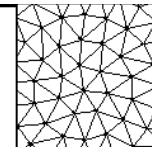


Why numerical methods



Example: seismic wave propagation

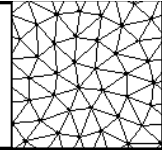




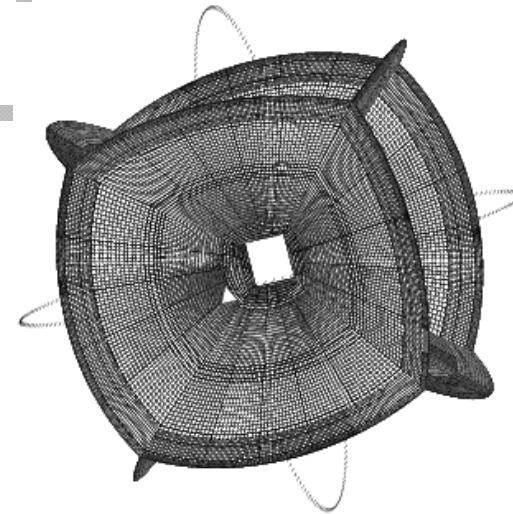
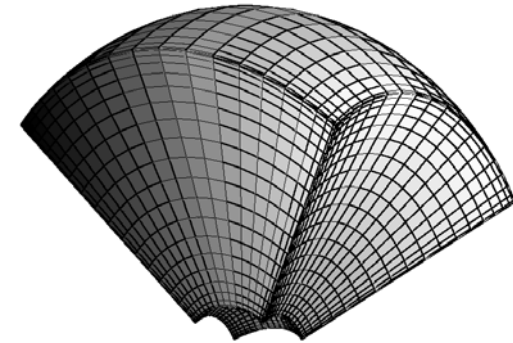


Spatial Scales and Memory

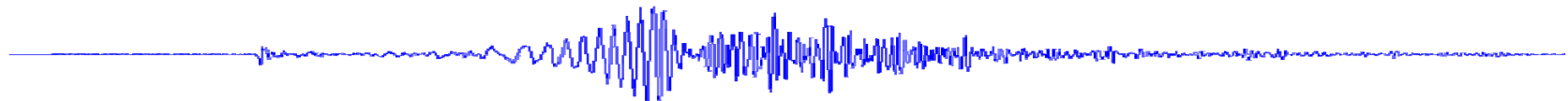
(back of the envelope)

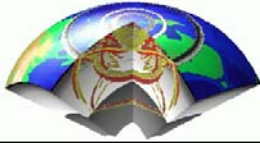


Highest frequency:	0.1 Hz
Shortest wavelength:	20 km (crust)
Shortest wavelength:	50 km (mantle)
Grid points per wavelength:	5
Grid spacing:	2000 m (crust)
Grid spacing:	5000 m (mantle)

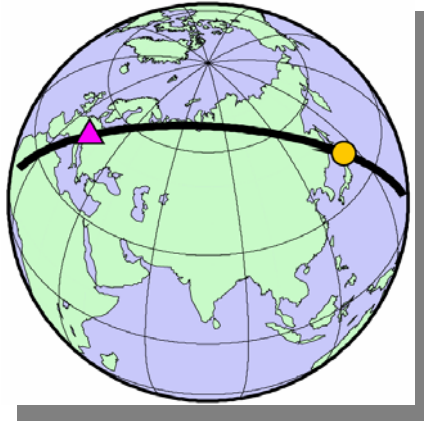
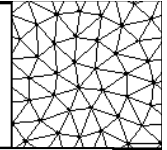


Required grid points: $O(10^9)$
Required memory: $O(100 \text{ GBytes})$

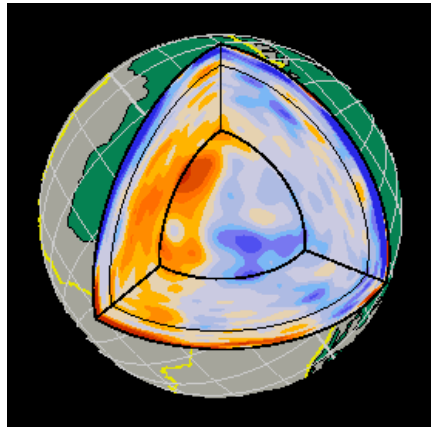
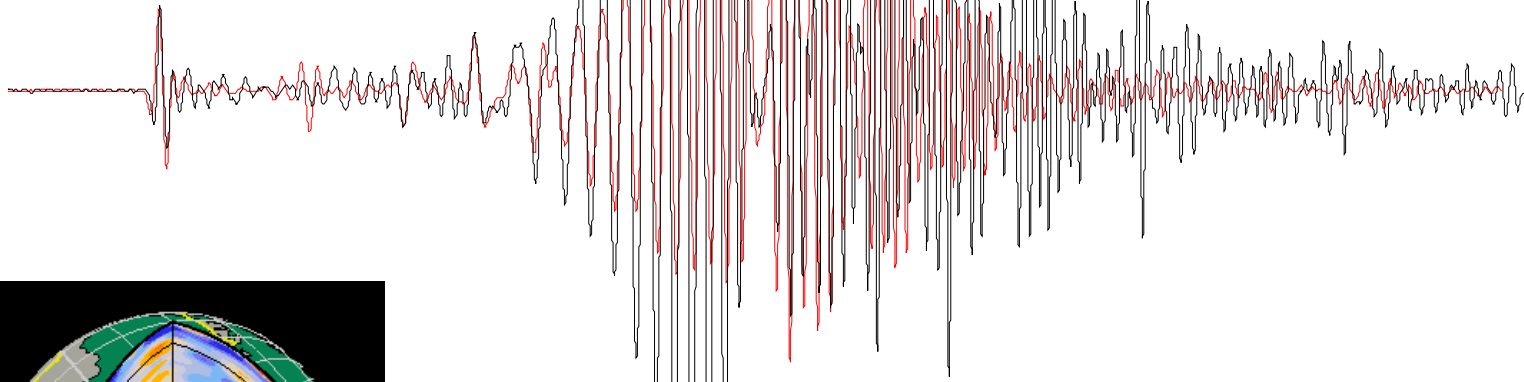




Data fitting - Inversion



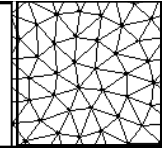
$T > 20s$



— Data
— Synthetics



Partial Differential Equations in Geophysics



$$\partial_t^2 p = c^2 \Delta p + s$$
$$\Delta = (\partial_x^2 + \partial_y^2 + \partial_z^2)$$

p	pressure
c	acoustic wave speed
s	sources

The acoustic wave equation

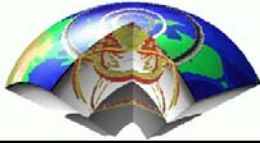
- seismology
- acoustics
- oceanography
- meteorology

$$\partial_t C = k \Delta C - \mathbf{v} \cdot \nabla C - RC + p$$

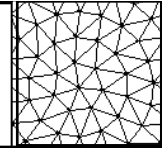
C	tracer concentration
k	diffusivity
\mathbf{v}	flow velocity
R	reactivity
p	sources

Diffusion, advection, Reaction

- geodynamics
- oceanography
- meteorology
- geochemistry
- sedimentology
- geophysical fluid dynamics



Numerical methods: properties

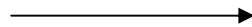


Finite differences



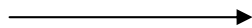
- time-dependent PDEs
- seismic wave propagation
- geophysical fluid dynamics
- Maxwell's equations
- Ground penetrating radar
- > **robust, simple concept, easy to parallelize, regular grids, explicit method**

Finite elements



- static and time-dependent PDEs
- seismic wave propagation
- geophysical fluid dynamics
- all problems
- > **implicit approach, matrix inversion, well founded, irregular grids, more complex algorithms, engineering problems**

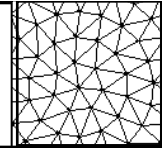
Finite volumes



- time-dependent PDEs
- seismic wave propagation
- mainly fluid dynamics
- > **robust, simple concept, irregular grids, explicit method**



Other Numerical methods:

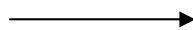


Particle-based methods



- lattice gas methods
- molecular dynamics
- granular problems
- fluid flow
- earthquake simulations
- > **very heterogeneous problems, nonlinear problems**

Boundary element methods

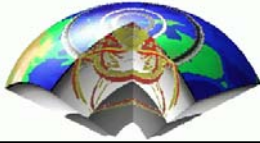


- problems with boundaries (rupture)
- based on analytical solutions
- only discretization of planes
- > **good for problems with special boundary conditions (rupture, cracks, etc)**

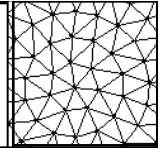
Pseudospectral methods



- orthogonal basis functions, special case of FD
- spectral accuracy of space derivatives
- wave propagation, GPR
- > **regular grids, explicit method, problems with strongly heterogeneous media**



What is a finite difference?



Common definitions of the derivative of $f(x)$:

$$\partial_x f = \lim_{dx \rightarrow 0} \frac{f(x + dx) - f(x)}{dx}$$

$$\partial_x f = \lim_{dx \rightarrow 0} \frac{f(x) - f(x - dx)}{dx}$$

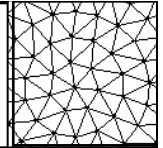
$$\partial_x f = \lim_{dx \rightarrow 0} \frac{f(x + dx) - f(x - dx)}{2dx}$$

These are all correct definitions in the limit $dx \rightarrow 0$.

But we want dx to remain **FINITE**



What is a finite difference?



The equivalent **approximations** of the derivatives are:

$$\partial_x f^+ \approx \frac{f(x + dx) - f(x)}{dx}$$

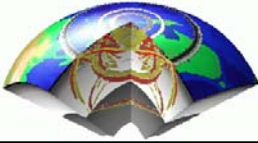
forward difference

$$\partial_x f^- \approx \frac{f(x) - f(x - dx)}{dx}$$

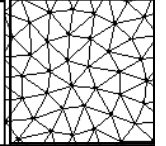
backward difference

$$\partial_x f \approx \frac{f(x + dx) - f(x - dx)}{2dx}$$

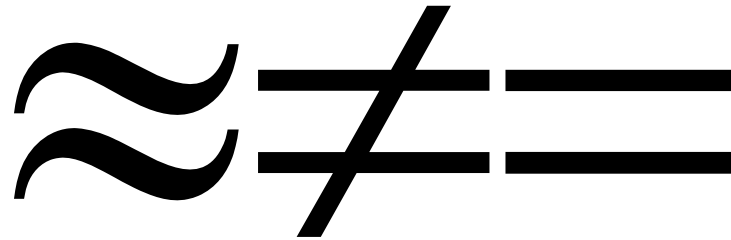
centered difference



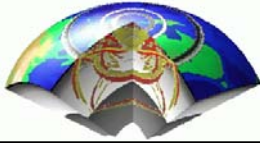
The **big** question:



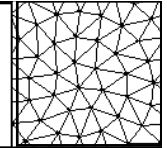
How good are the FD approximations?



This leads us to Taylor series....



Our first FD algorithm (ac1d.m) !



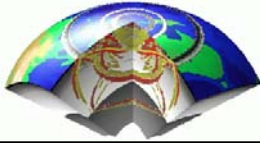
$$\partial_t^2 p = c^2 \Delta p + s$$
$$\Delta = (\partial_x^2 + \partial_y^2 + \partial_z^2)$$

P pressure
c acoustic wave speed
s sources

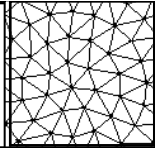
Problem: Solve the 1D acoustic wave equation using the finite Difference method.

Solution:

$$p(t + dt) = \frac{c^2 dt^2}{dx^2} [p(x + dx) - 2p(x) + p(x - dx)]$$
$$+ 2p(t) - p(t - dt) + s dt^2$$



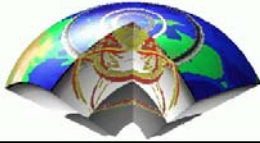
Problems: Stability



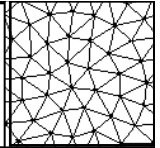
$$p(t + dt) = \frac{c^2 dt^2}{dx^2} [p(x + dx) - 2p(x) + p(x - dx)] + 2p(t) - p(t - dt) + sdt^2$$

Stability: Careful analysis using harmonic functions shows that a stable numerical calculation is subject to special conditions (conditional stability). This holds for many numerical problems.

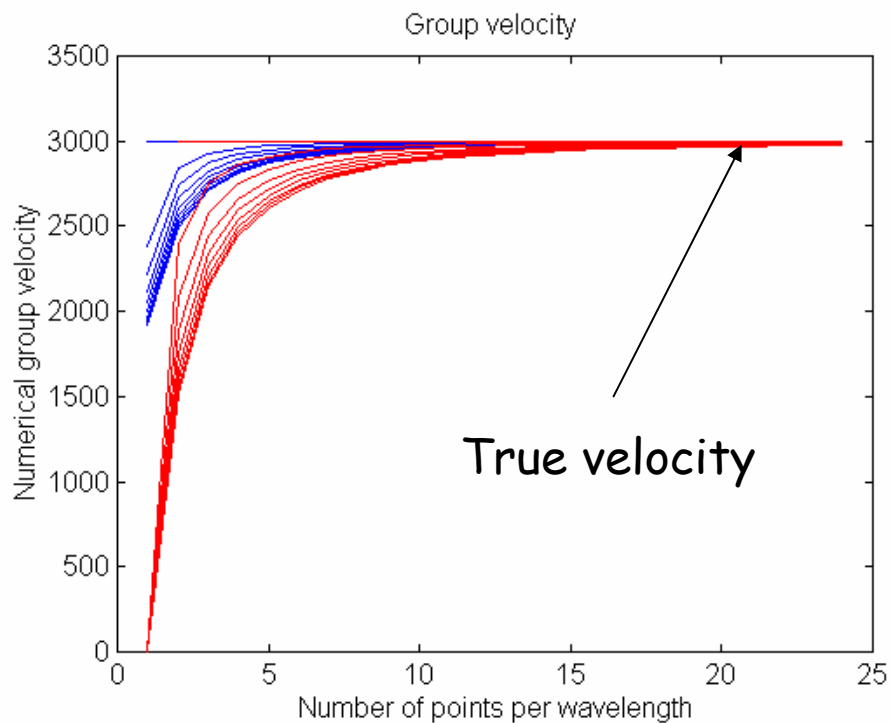
$$c \frac{dt}{dx} \leq \varepsilon \approx 1$$



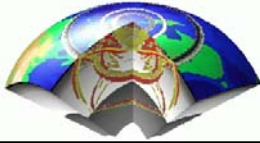
Problems: Dispersion



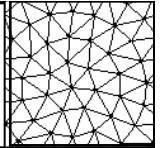
$$p(t + dt) = \frac{c^2 dt^2}{dx^2} [p(x + dx) - 2p(x) + p(x - dx)] + 2p(t) - p(t - dt) + sdt^2$$



Dispersion: The numerical approximation has artificial dispersion, in other words, the wave speed becomes frequency dependent. You have to find a frequency bandwidth where this effect is small. The solution is to use a sufficient number of **grid points per wavelength**.



Our first FD code!



$$p(t + dt) = \frac{c^2 dt^2}{dx^2} [p(x + dx) - 2p(x) + p(x - dx)] + 2p(t) - p(t - dt) + sdt^2$$

```
% Time stepping
for i=1:nt,

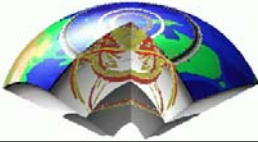
    % FD

    disp(sprintf(' Time step : %i',i));

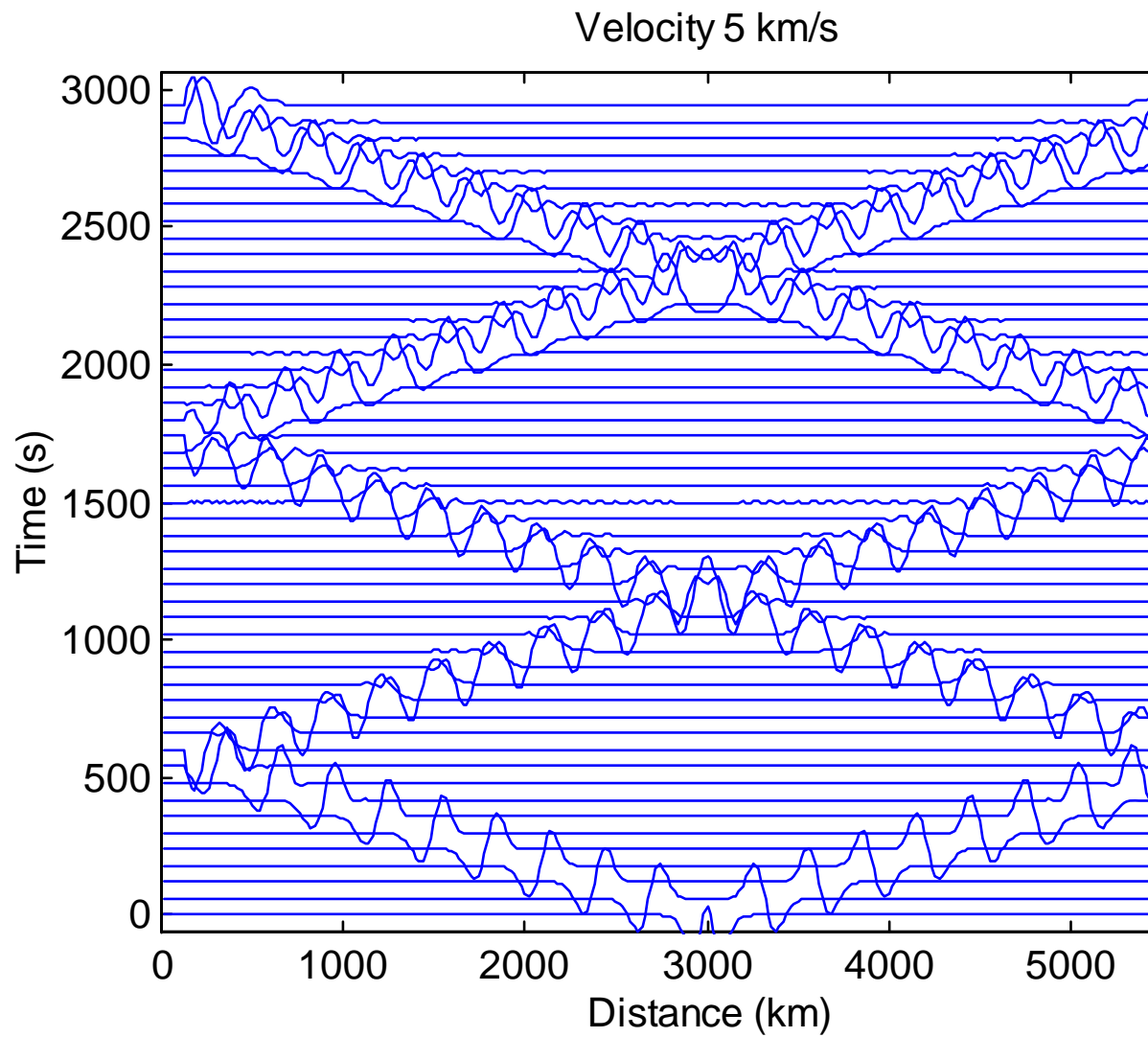
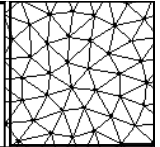
    for j=2:nx-1
        d2p(j)=(p(j+1)-2*p(j)+p(j-1))/dx^2; % space derivative
    end
    pnew=2*p-pold+d2p*dt^2;                % time extrapolation
    pnew(nx/2)=pnew(nx/2)+src(i)*dt^2;    % add source term
    pold=p;                                % time levels
    p=pnew;
    p(1)=0;                                % set boundaries pressure free
    p(nx)=0;

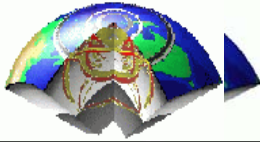
    % Display
    plot(x,p,'b-')
    title(' FD ')
    drawnow

end
```

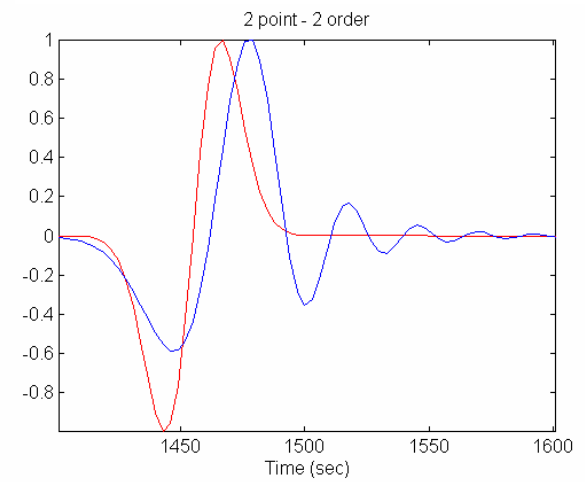
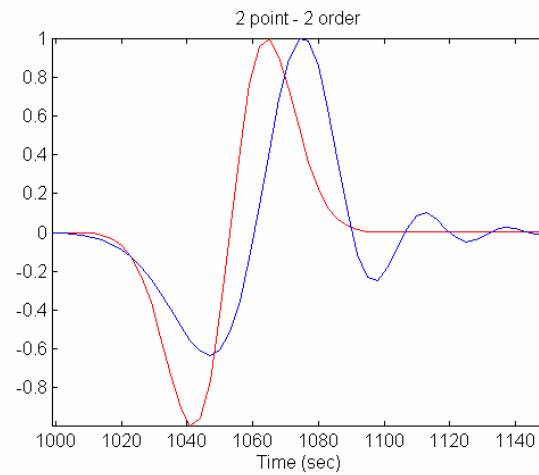
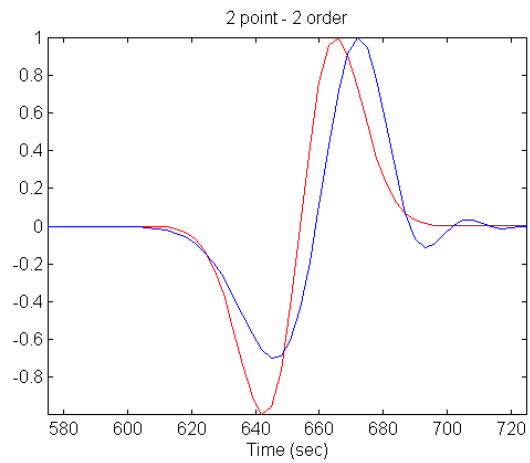
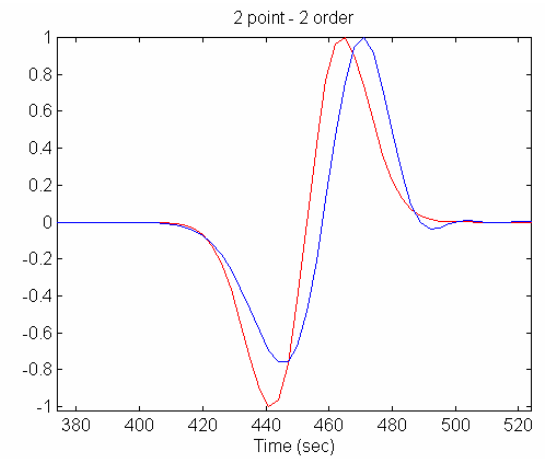
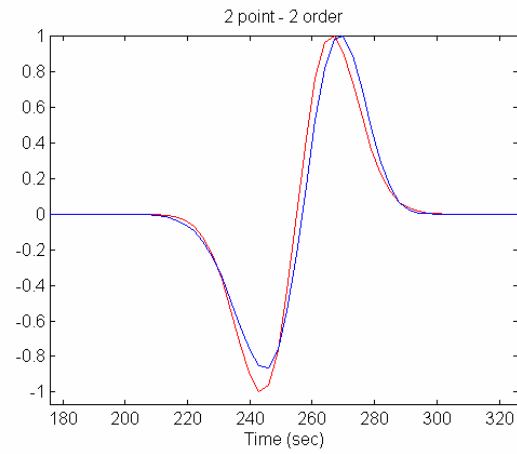
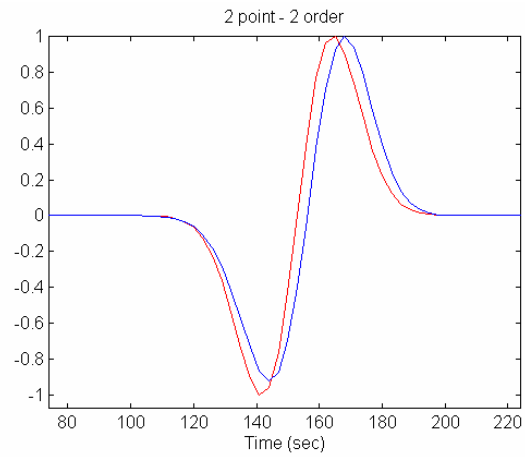
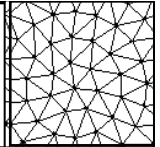


Snapshot Example



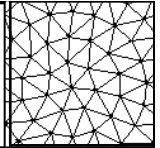


Seismogram Dispersion





Finite Differences - Summary



- Conceptually the most **simple** of the numerical methods and can be learned quite quickly
- Depending on the physical problem FD methods are **conditionally stable** (relation between time and space increment)
- FD methods have difficulties concerning the accurate implementation of **boundary conditions** (e.g. free surfaces, absorbing boundaries)
- FD methods are usually **explicit** and therefore very easy to implement and efficient on **parallel computers**
- FD methods work best on regular, rectangular grids